

The quadratic numerical range: A new concept for localizing spectra and more

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(jointly with H. Langer, A. Markus, V. Matsaev, M. Wagenhofer)

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\mathcal{H} Hilbert space, $\mathcal{A} \in L(\mathcal{H})$ (bounded linear operator)

Numerical range:

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- $\lambda_0 \in W(\mathcal{A})$ corner $\implies \lambda_0 \in \sigma_p(\mathcal{A}),$
- $\|(\mathcal{A} - \lambda)^{-1}\| \leq \frac{1}{\text{dist}(\lambda, W(\mathcal{A}))}, \quad \lambda \notin \overline{W(\mathcal{A})},$
- $\mathcal{A} = \mathcal{A}^* \geq \alpha \implies \lambda_n = \min_{\dim \mathcal{L}=n} \max_{\substack{x \in \mathcal{L} \\ \|x\|=1}} (\mathcal{A}x, x)$
-

1. The quadratic numerical range (QNR)

Now: $\mathcal{H} = \mathcal{H}_1 \times \mathcal{H}_2$ with Hilbert spaces $\mathcal{H}_1, \mathcal{H}_2$,

$$A = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \quad \text{in } \mathcal{H}_1 \times \mathcal{H}_2$$

with $A \in L(\mathcal{H}_1)$, $B \in L(\mathcal{H}_2, \mathcal{H}_1)$, $C \in L(\mathcal{H}_1, \mathcal{H}_2)$, and $D \in L(\mathcal{H}_2)$.

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Definition. (LT'98)

$$W^2(\mathcal{A}) := \left\{ \lambda \in \mathbb{C} : \det \begin{pmatrix} \overbrace{(Ax_1, x_1) - \lambda}^{=: \mathcal{A}_{x_1, x_2} - \lambda} & (Bx_2, x_1) \\ (Cx_1, x_2) & (Dx_2, x_2) - \lambda \end{pmatrix} = 0 \text{ for some} \right. \\ \left. x_1 \in \mathcal{H}_1, x_2 \in \mathcal{H}_2, \|x_1\| = \|x_2\| = 1 \right\} \\ = \bigcup_{\|x_1\| = \|x_2\| = 1} \sigma_p(\mathcal{A}_{x_1, x_2})$$

is called **quadratic numerical range (QNR)** of \mathcal{A} .

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Proof. (for $\lambda \in \sigma_p(\mathcal{A})$)

$$\mathcal{A} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \lambda \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \quad \text{with} \quad \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \neq 0.$$

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Then

$$\begin{aligned} (Ax_1, \hat{x}_1) + (Bx_2, \hat{x}_1) &= \lambda(x_1, \hat{x}_1), \\ Cx_1, \hat{x}_2) + (Dx_2, \hat{x}_2) &= \lambda(x_2, \hat{x}_2), \end{aligned}$$

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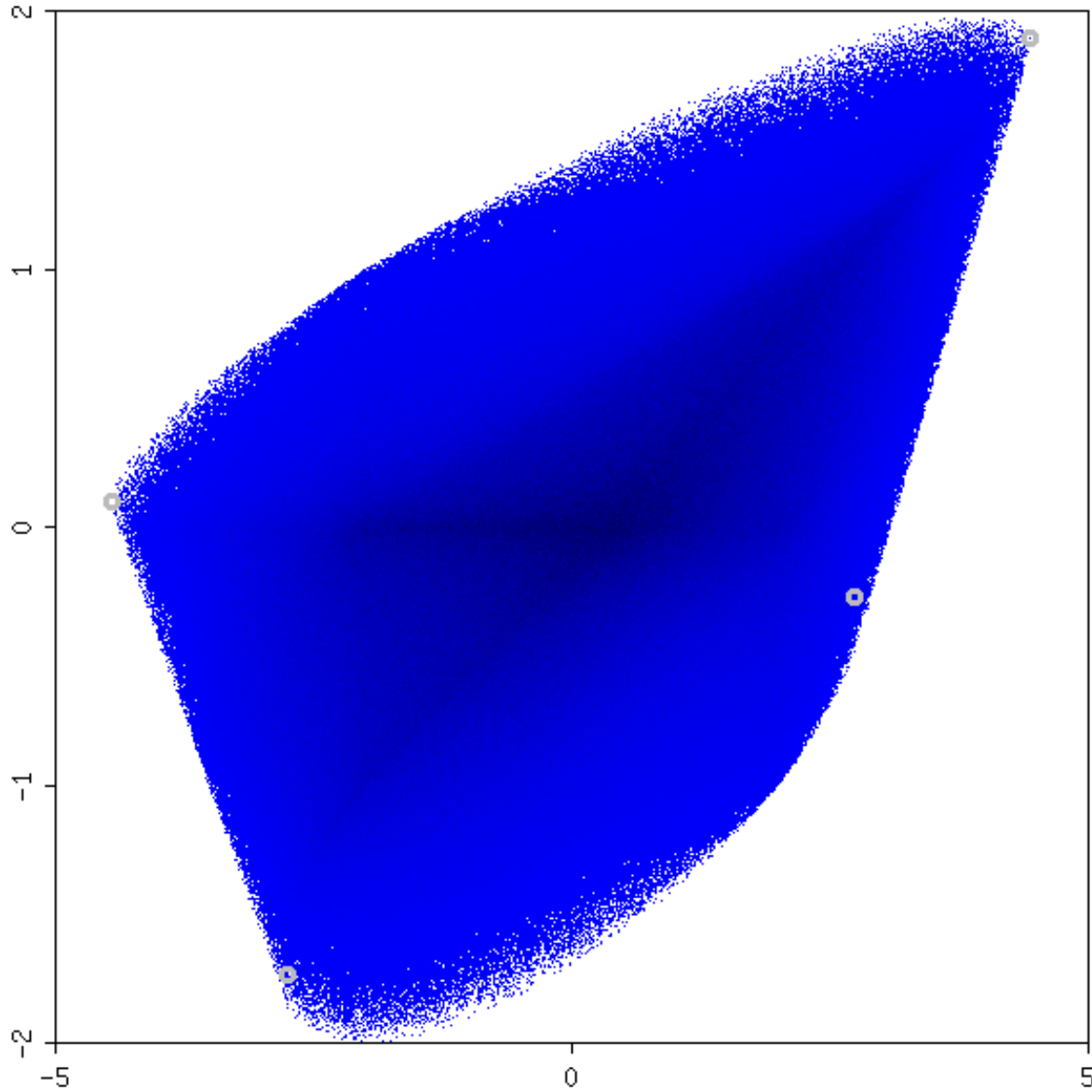
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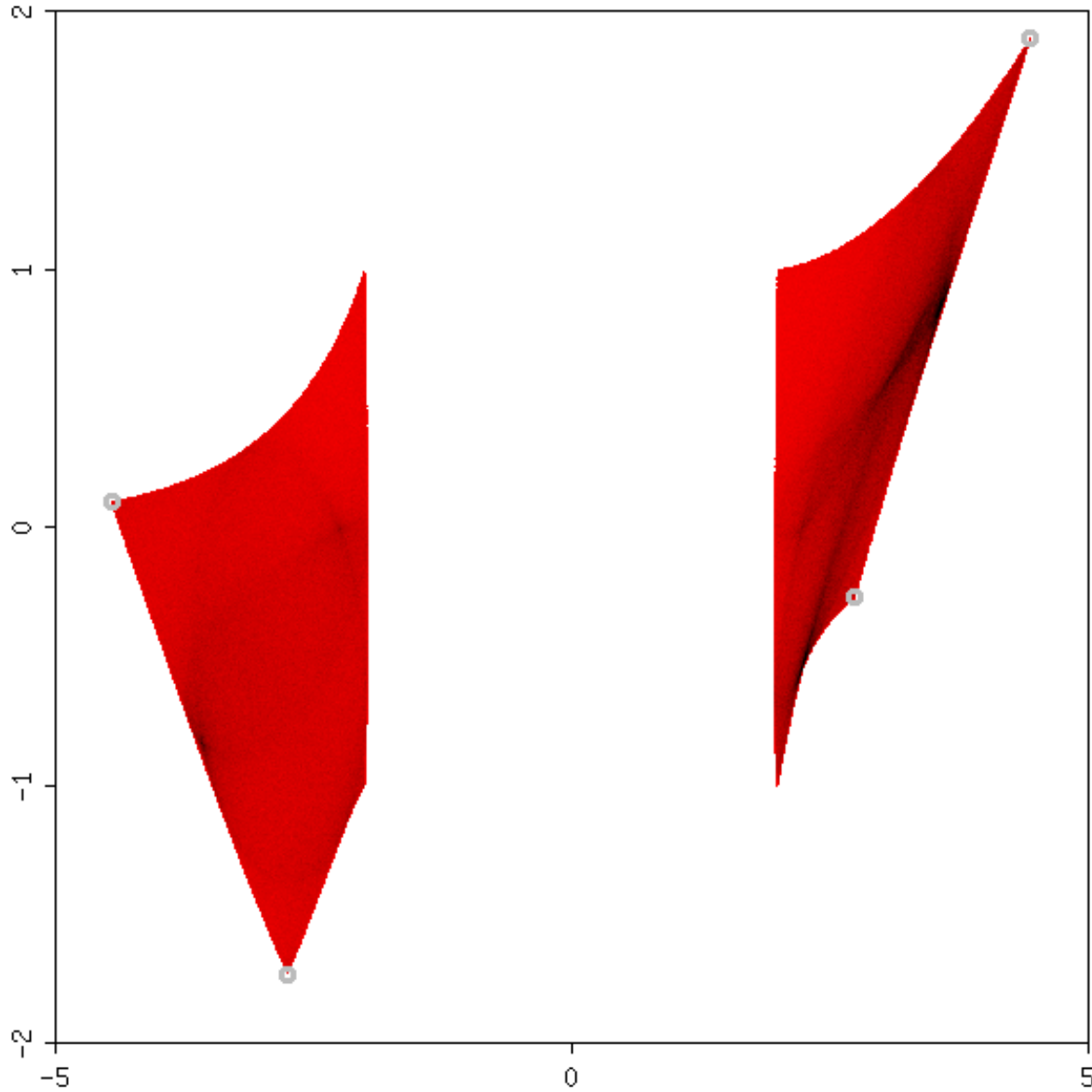
with $x_i =: \|x_i\| \hat{x}_i, \|\hat{x}_i\| = 1$, for $i = 1, 2$. Hence

$$\implies \mathcal{A}_{\hat{x}_1, \hat{x}_2} \begin{pmatrix} \|x_1\| \\ \|x_2\| \end{pmatrix} = \lambda \begin{pmatrix} \|x_1\| \\ \|x_2\| \end{pmatrix} \implies \lambda \in \sigma_p(\mathcal{A}_{\hat{x}_1, \hat{x}_2}) \subset W^2(\mathcal{A}). \quad \square$$



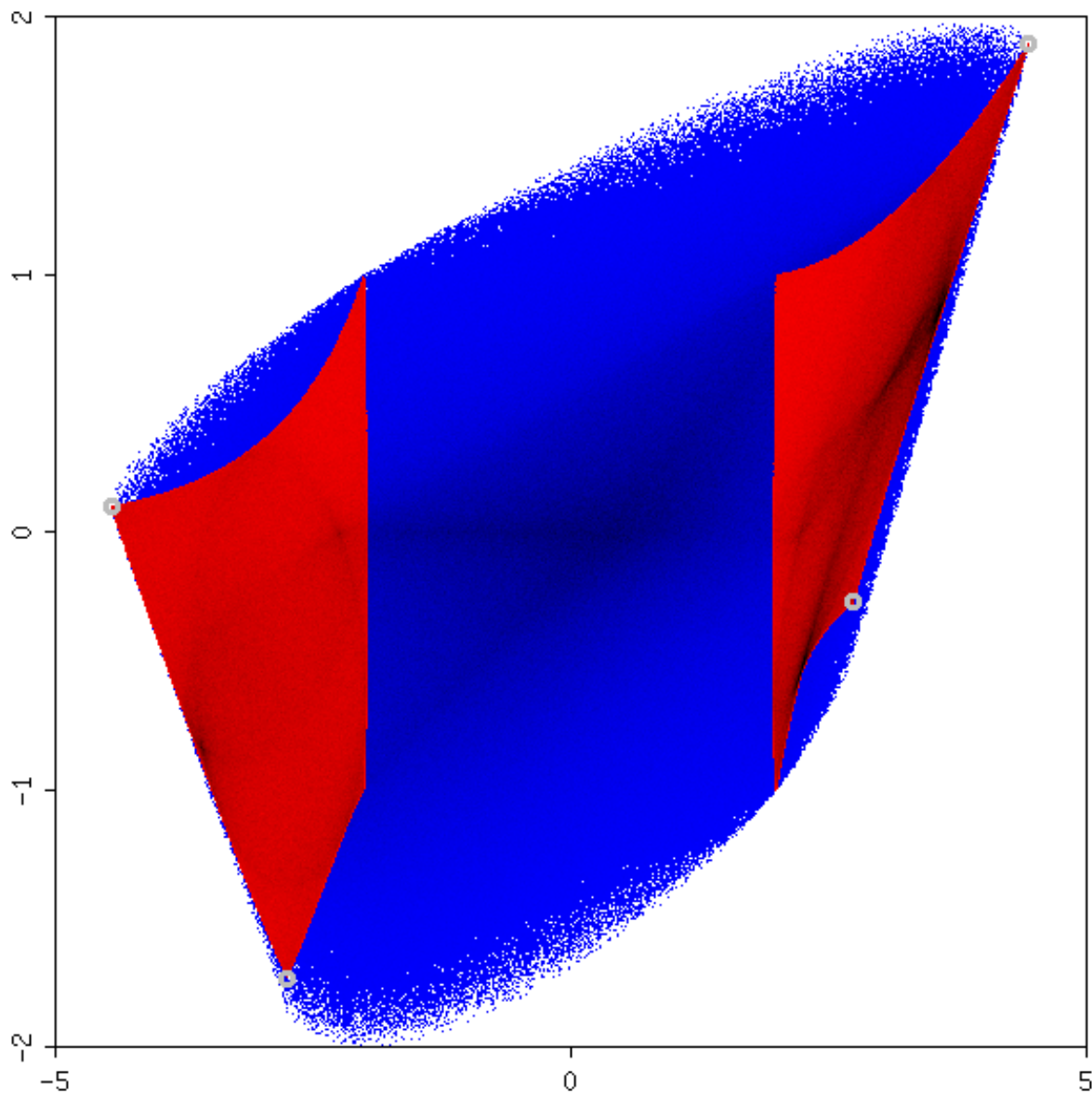
Numerical range of

$$\begin{pmatrix} 2 & i & 1 & 3+i \\ i & 2 & 3+i & 1 \\ 1 & 3+i & -2 & i \\ 3+i & 1 & i & -2 \end{pmatrix}$$



QNR of

$$\left(\begin{array}{cc|cc} 2 & i & 1 & 3+i \\ i & 2 & 3+i & 1 \\ \hline 1 & 3+i & -2 & i \\ 3+i & 1 & i & -2 \end{array} \right)$$

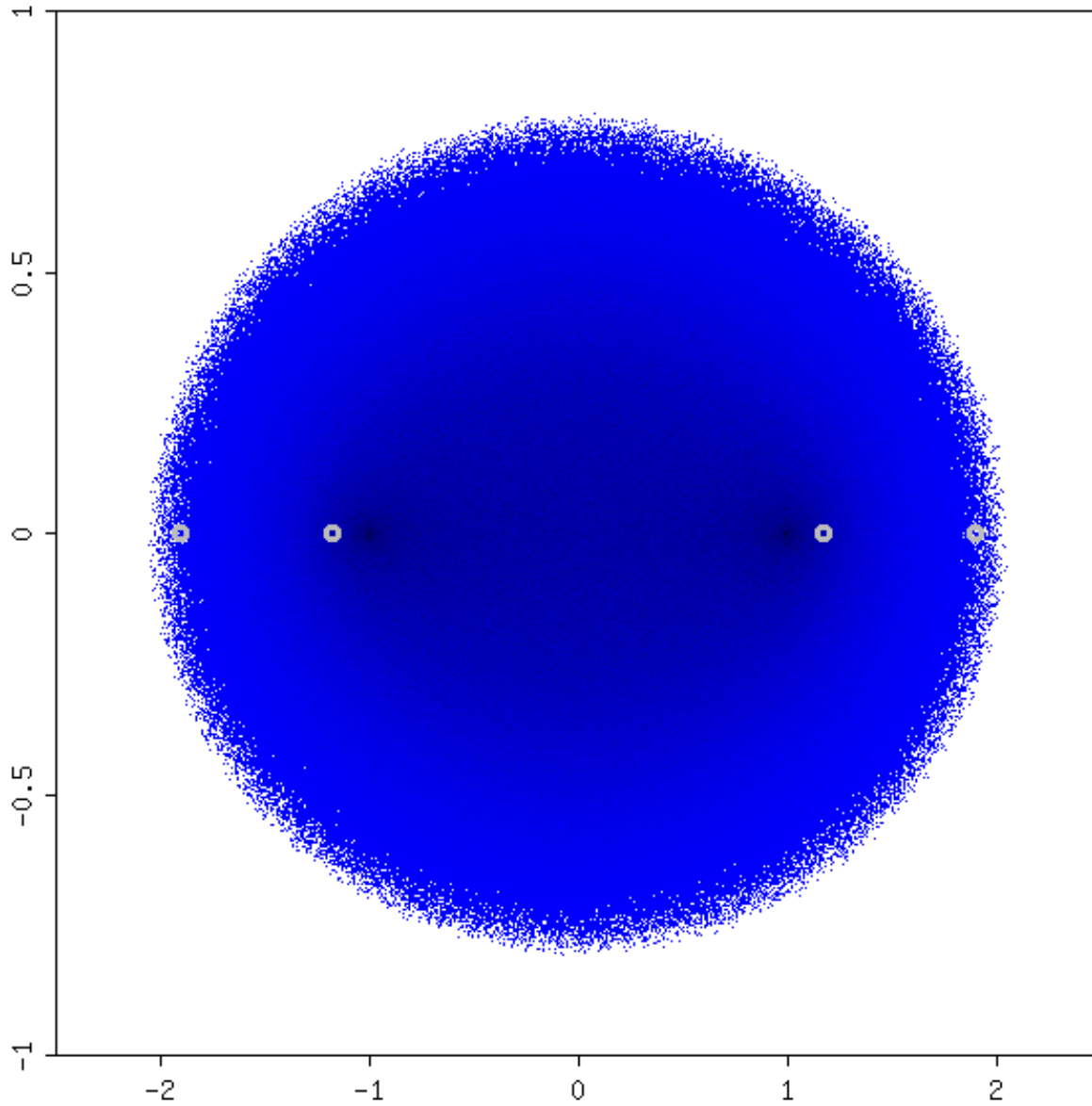


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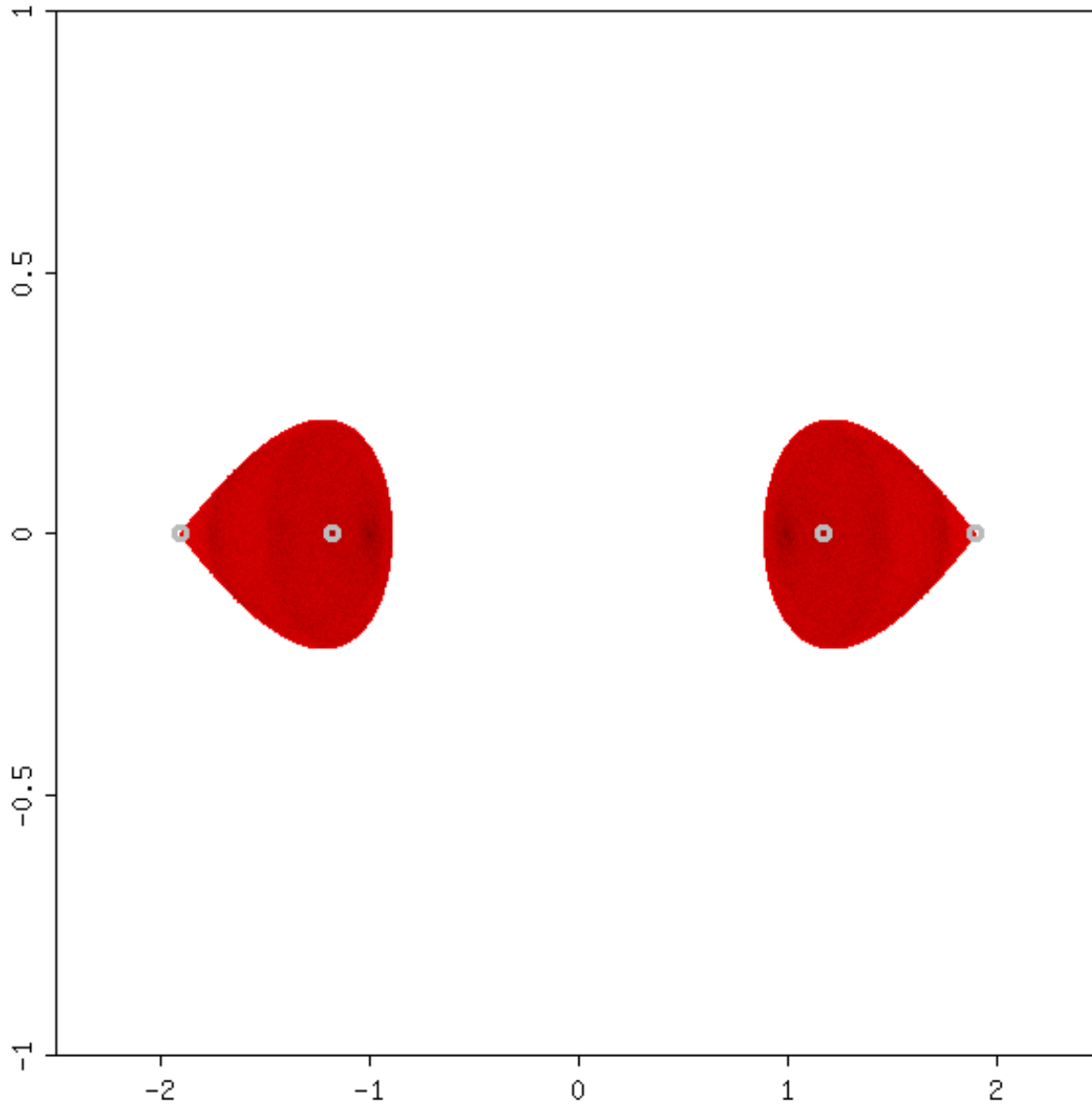
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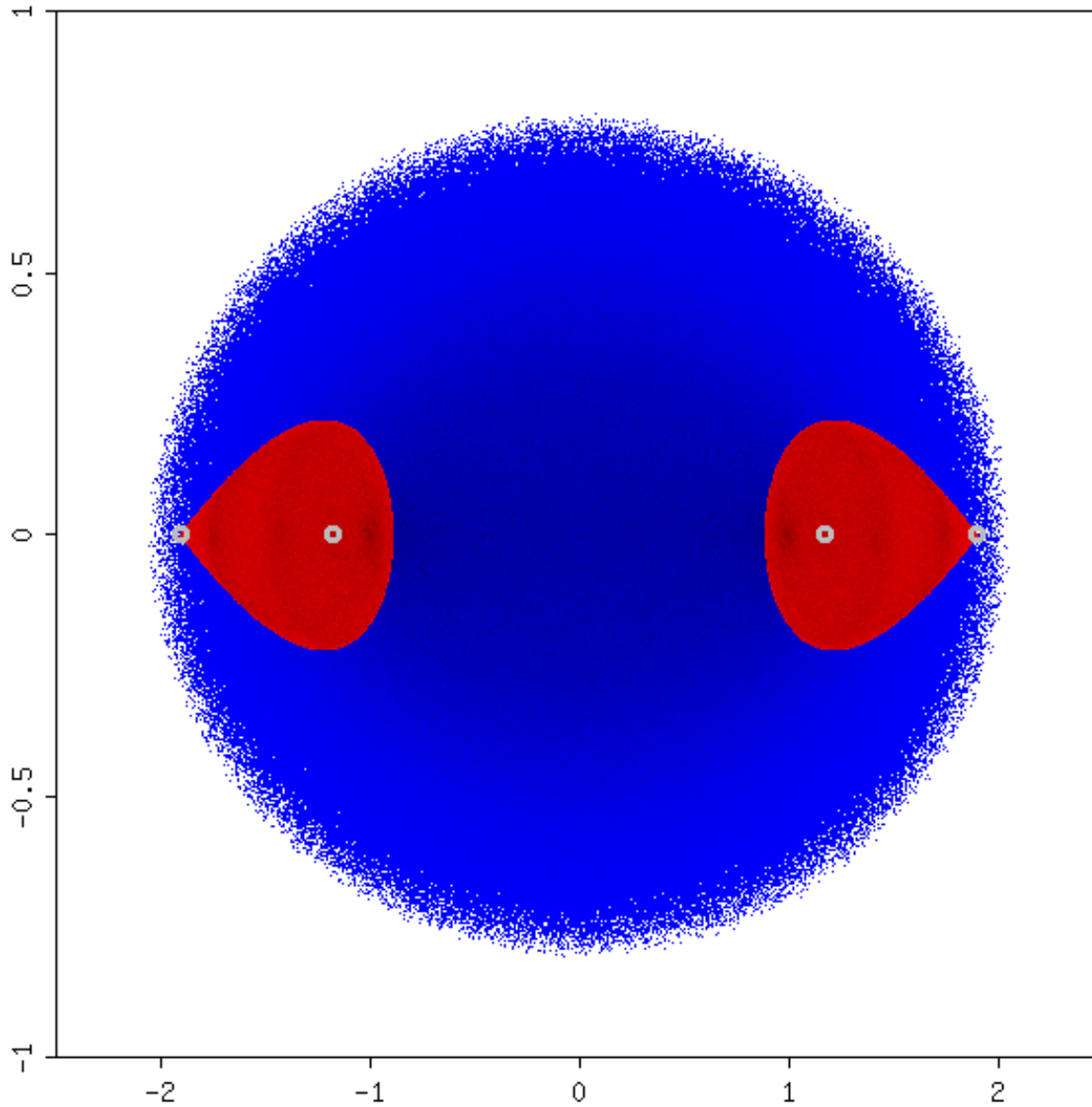
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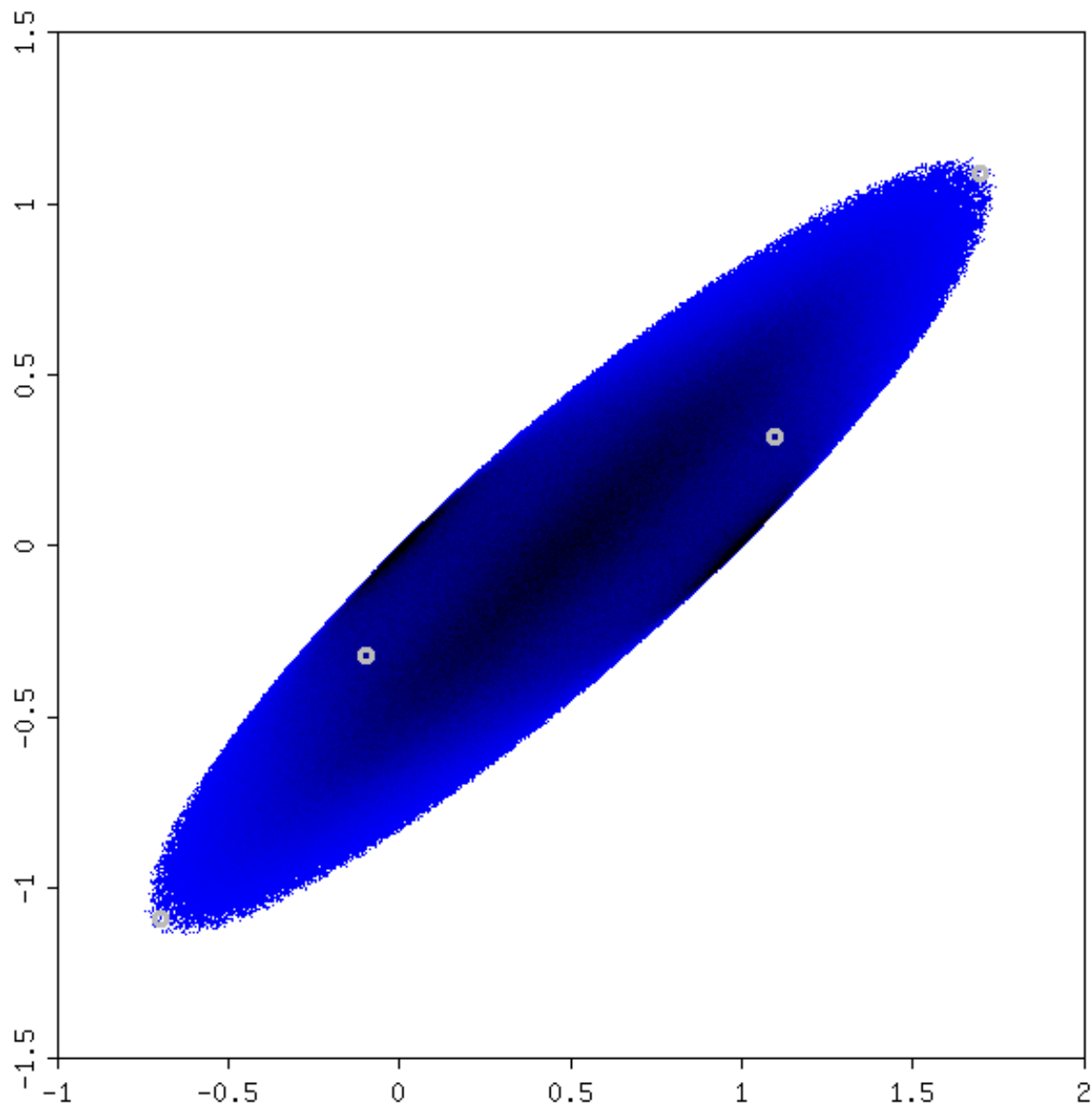


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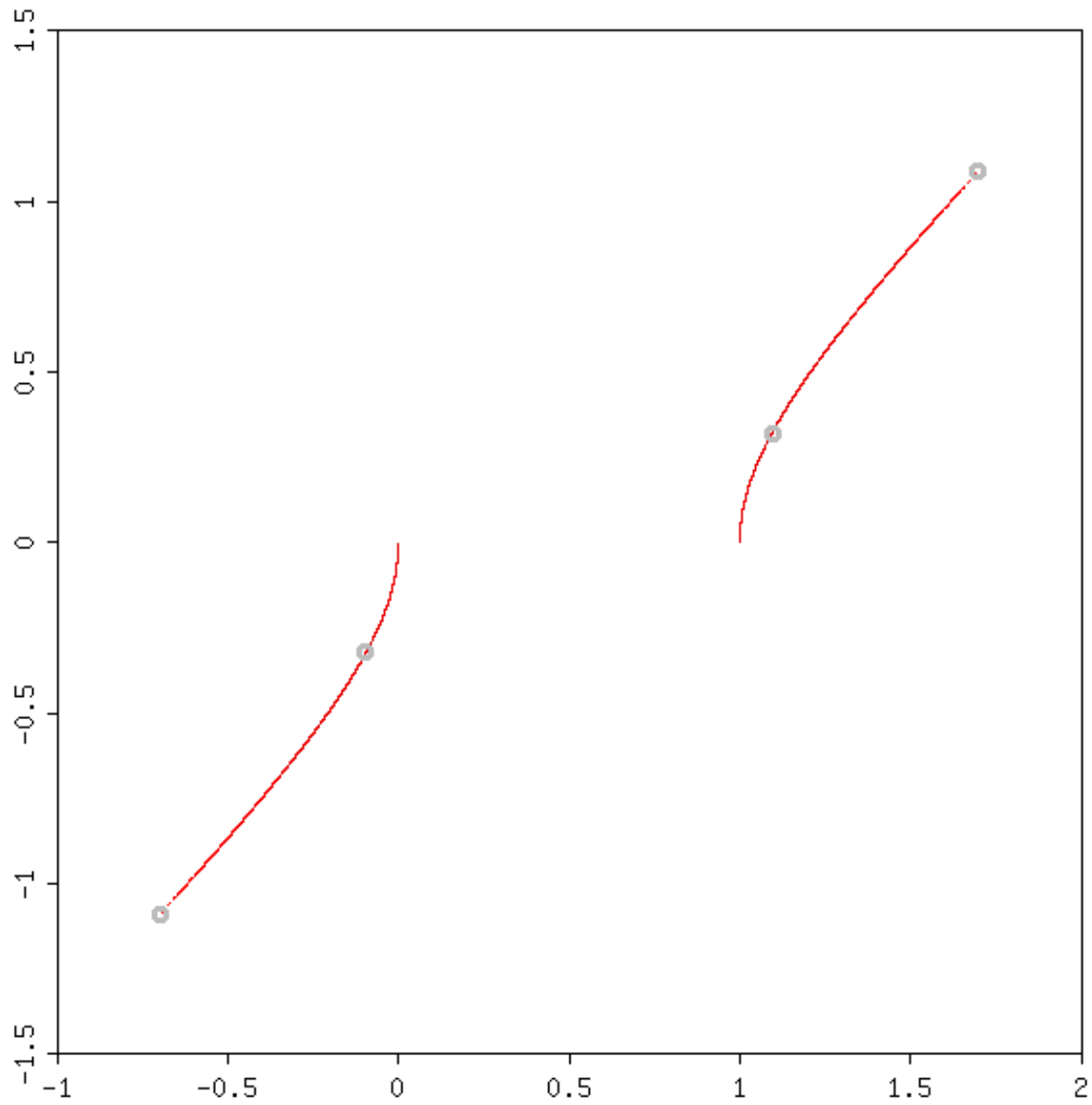
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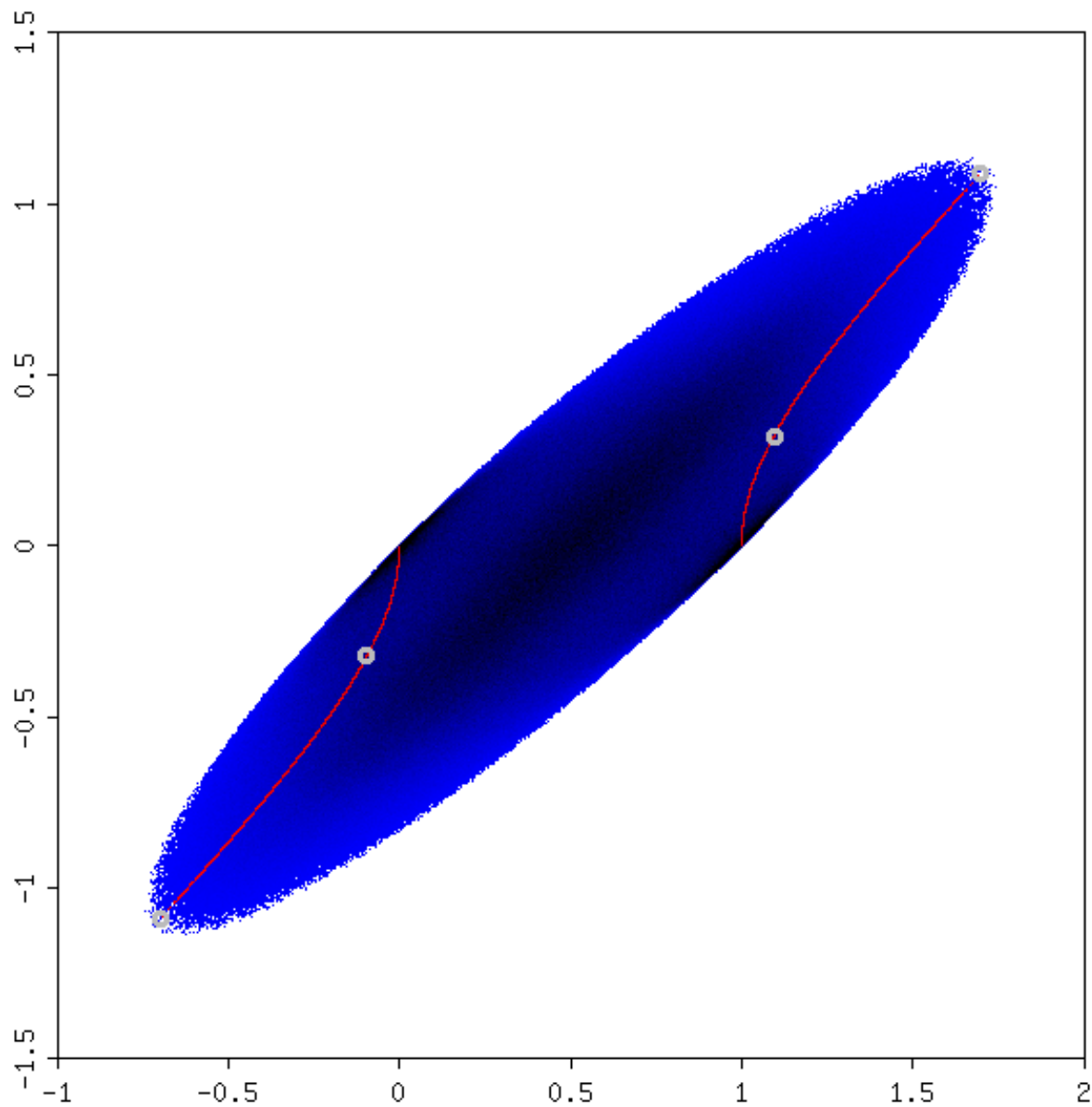
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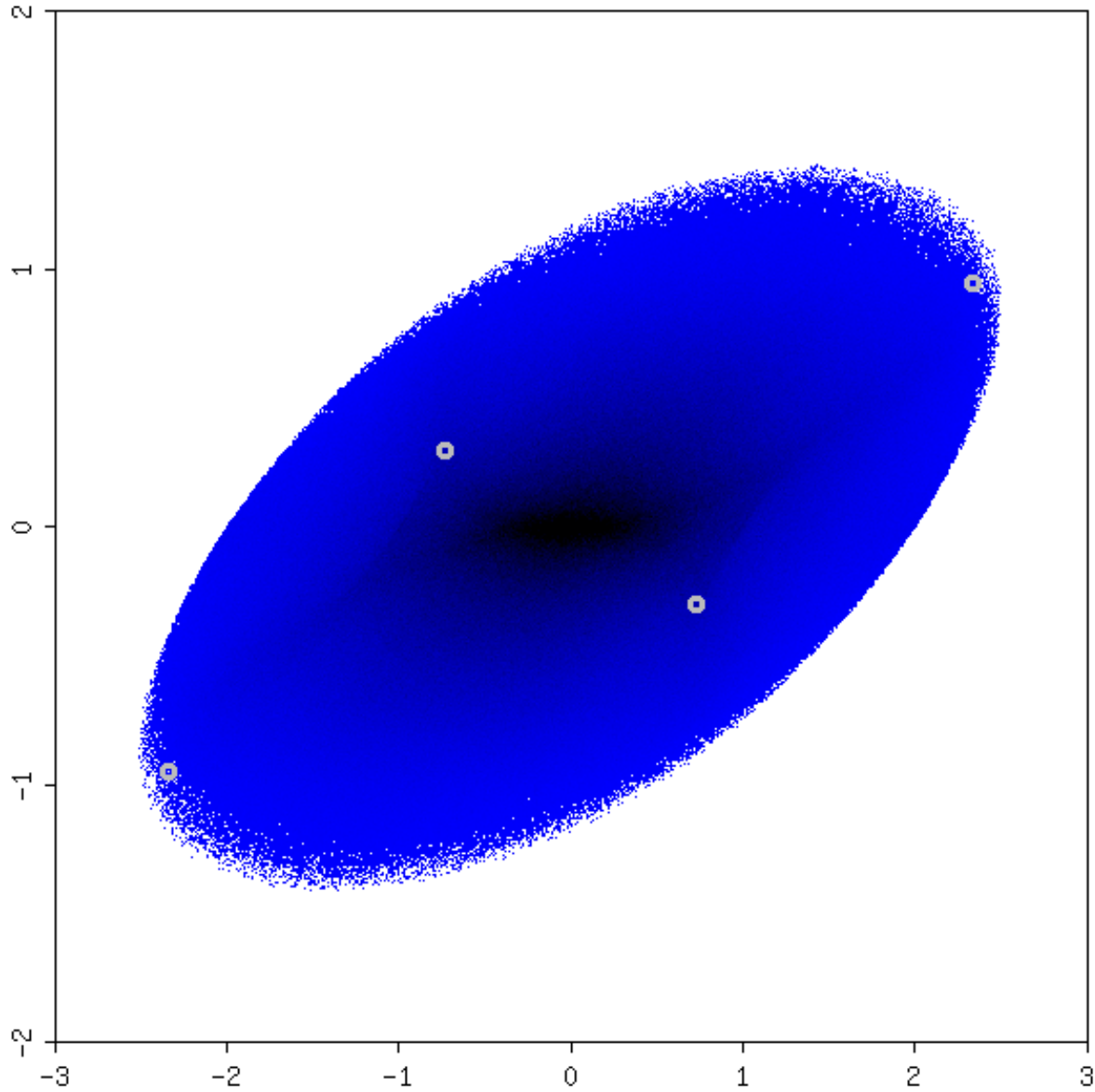


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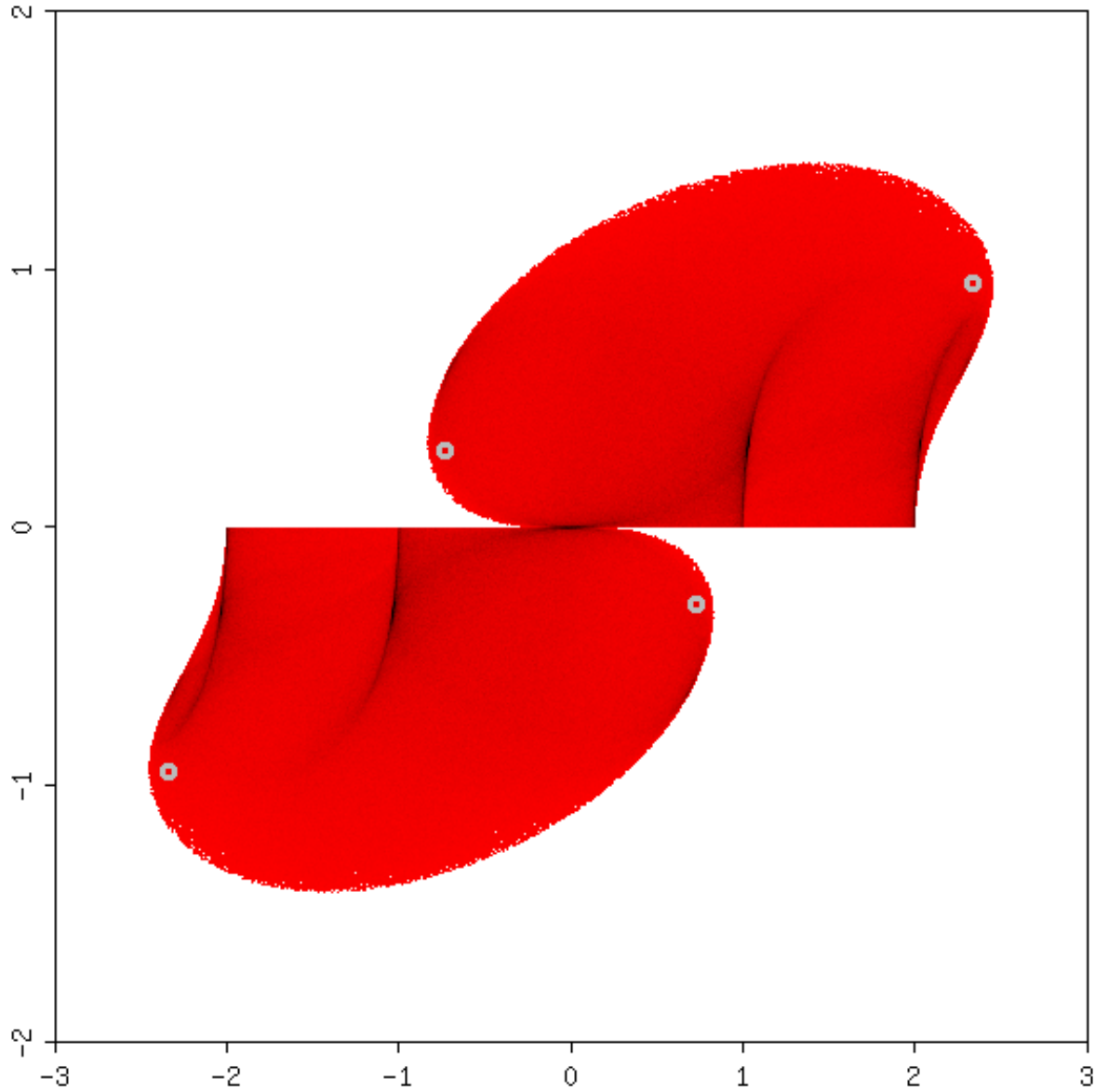
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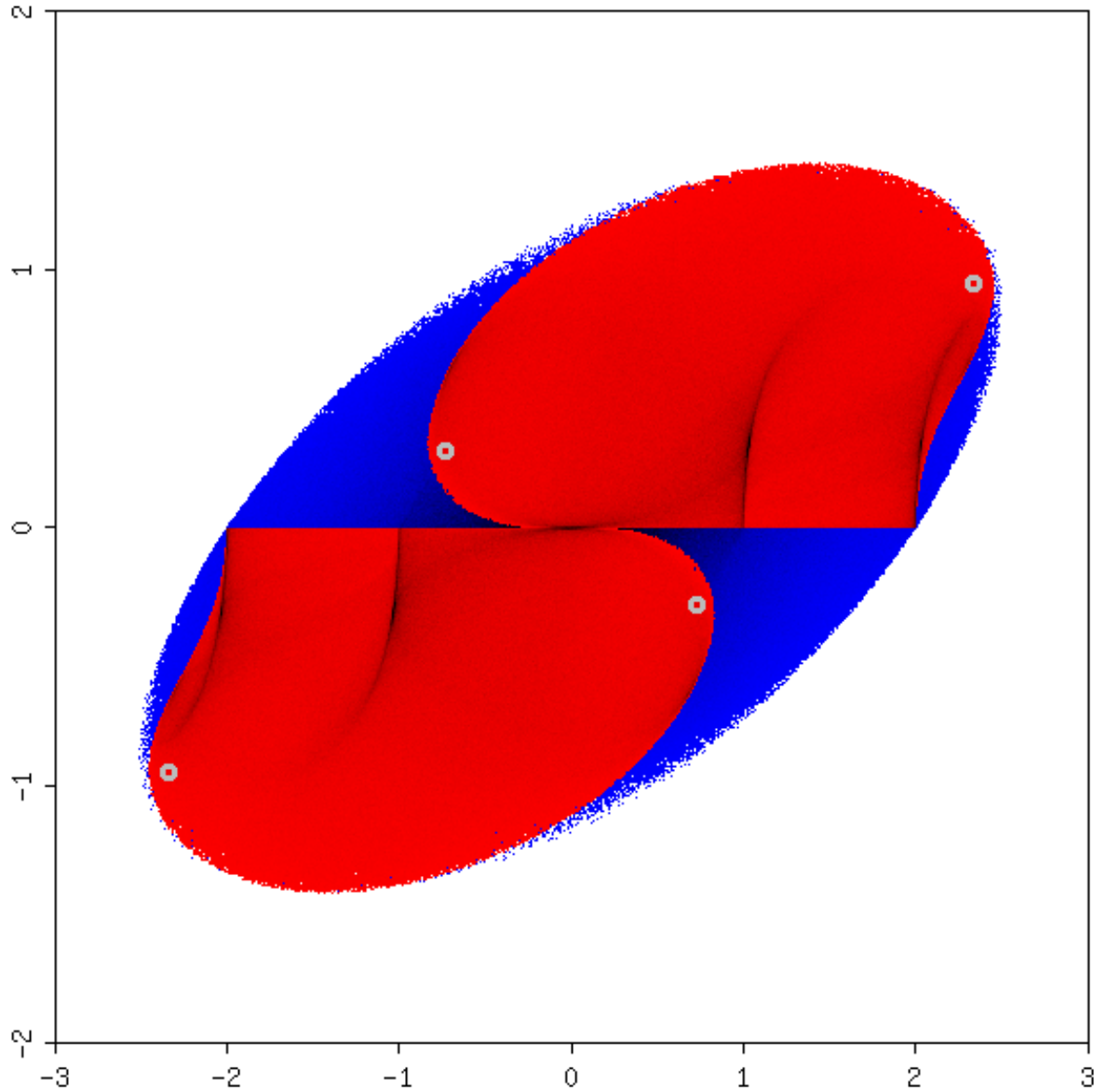
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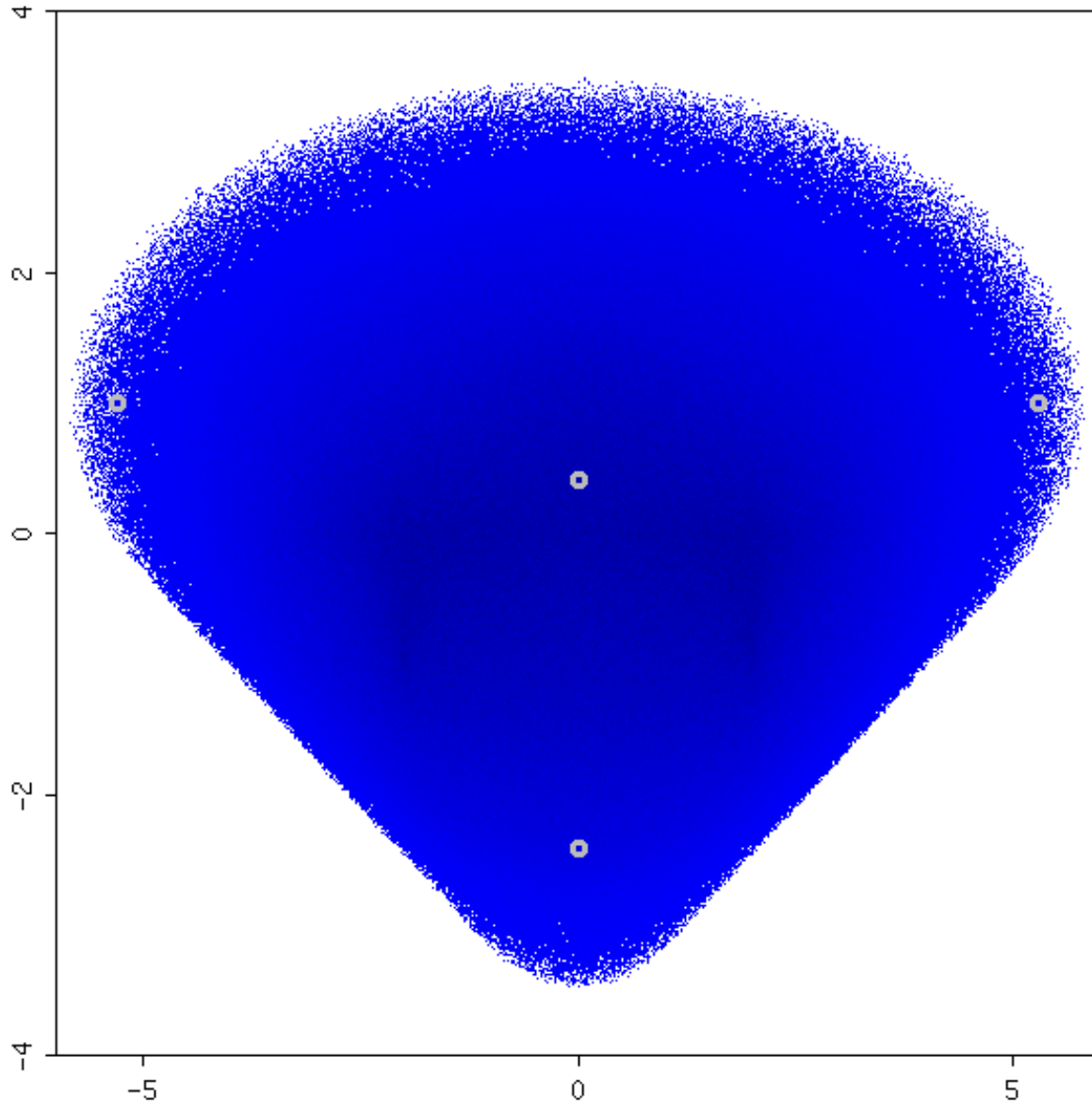


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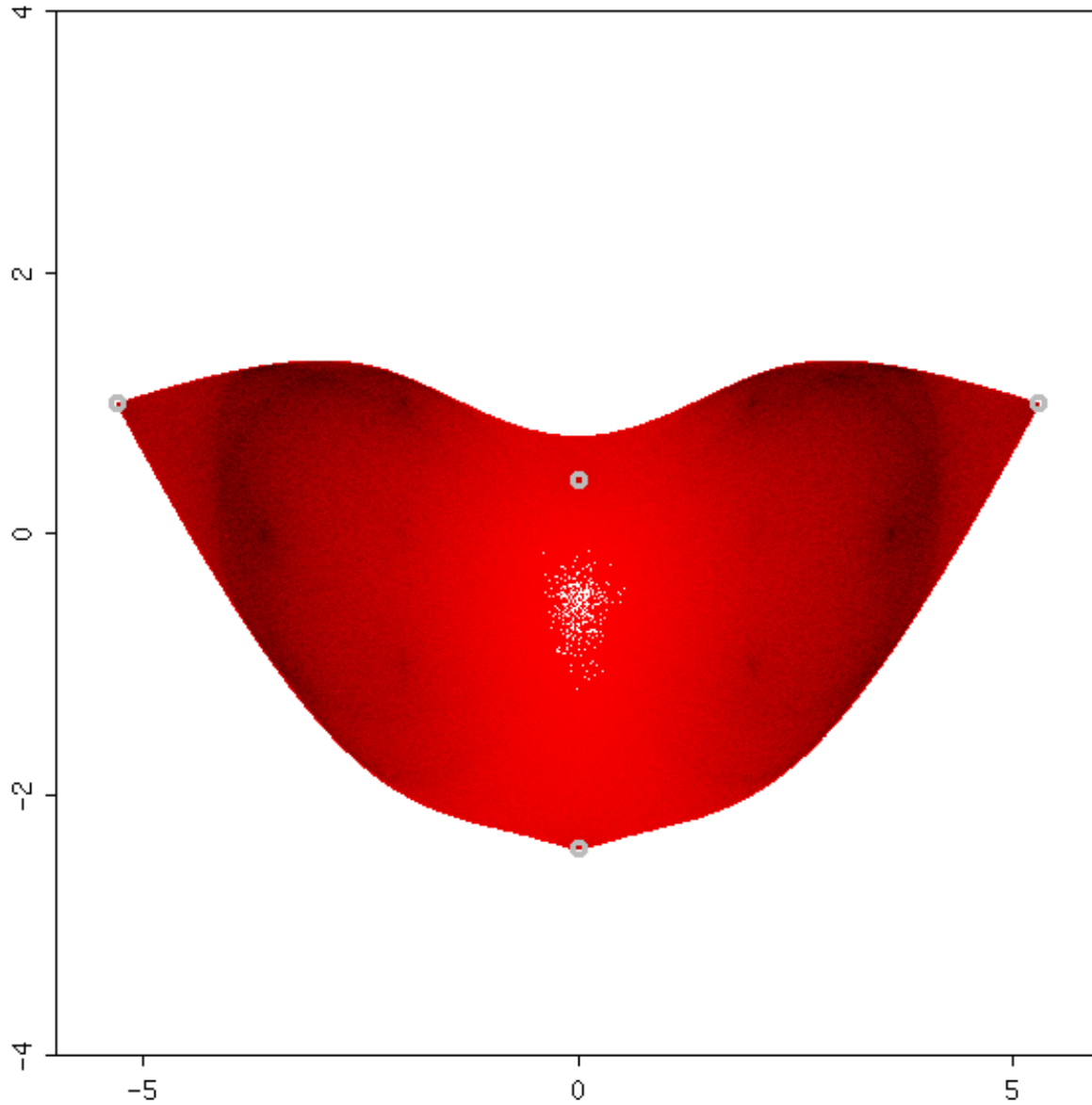
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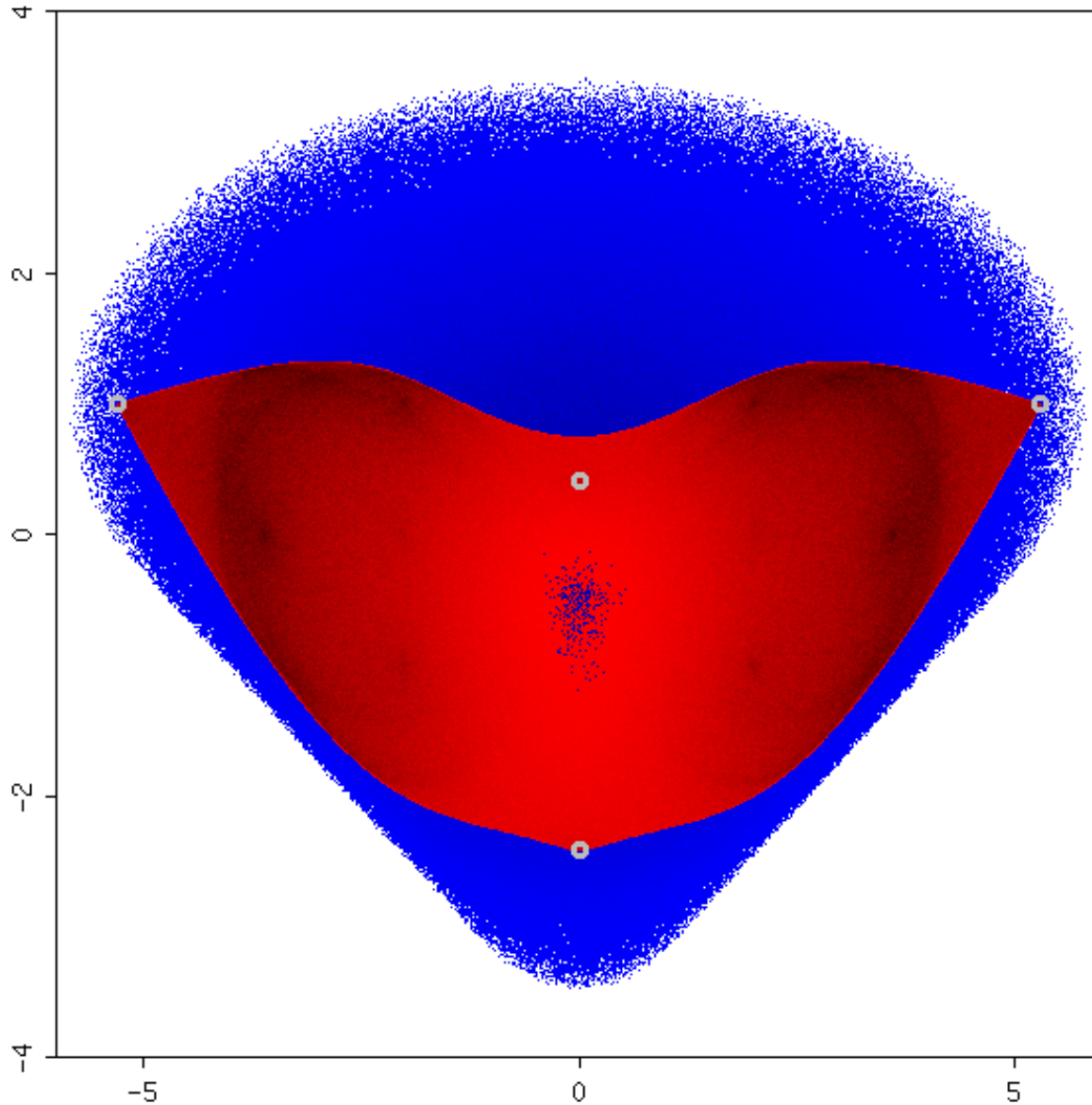
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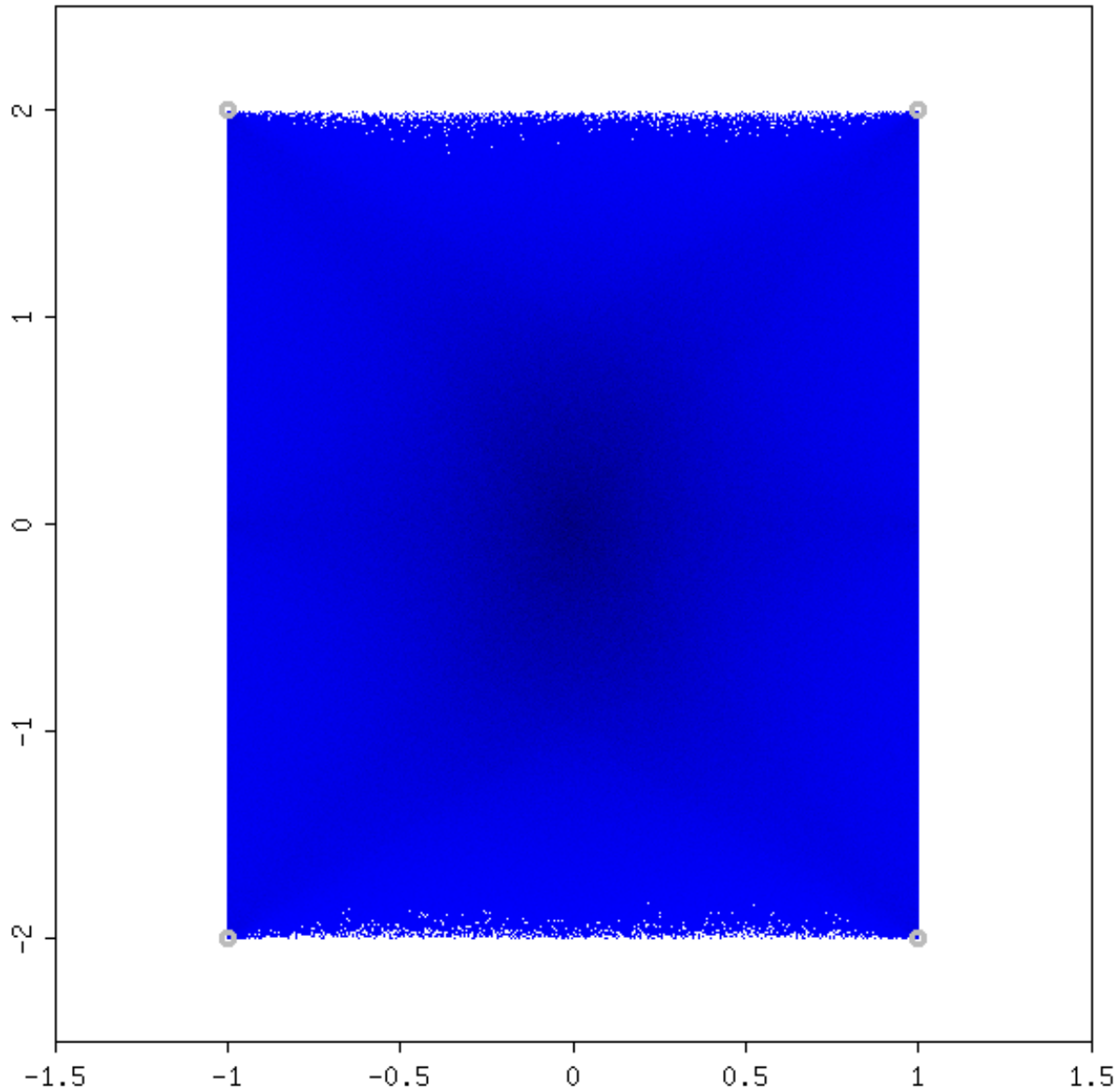


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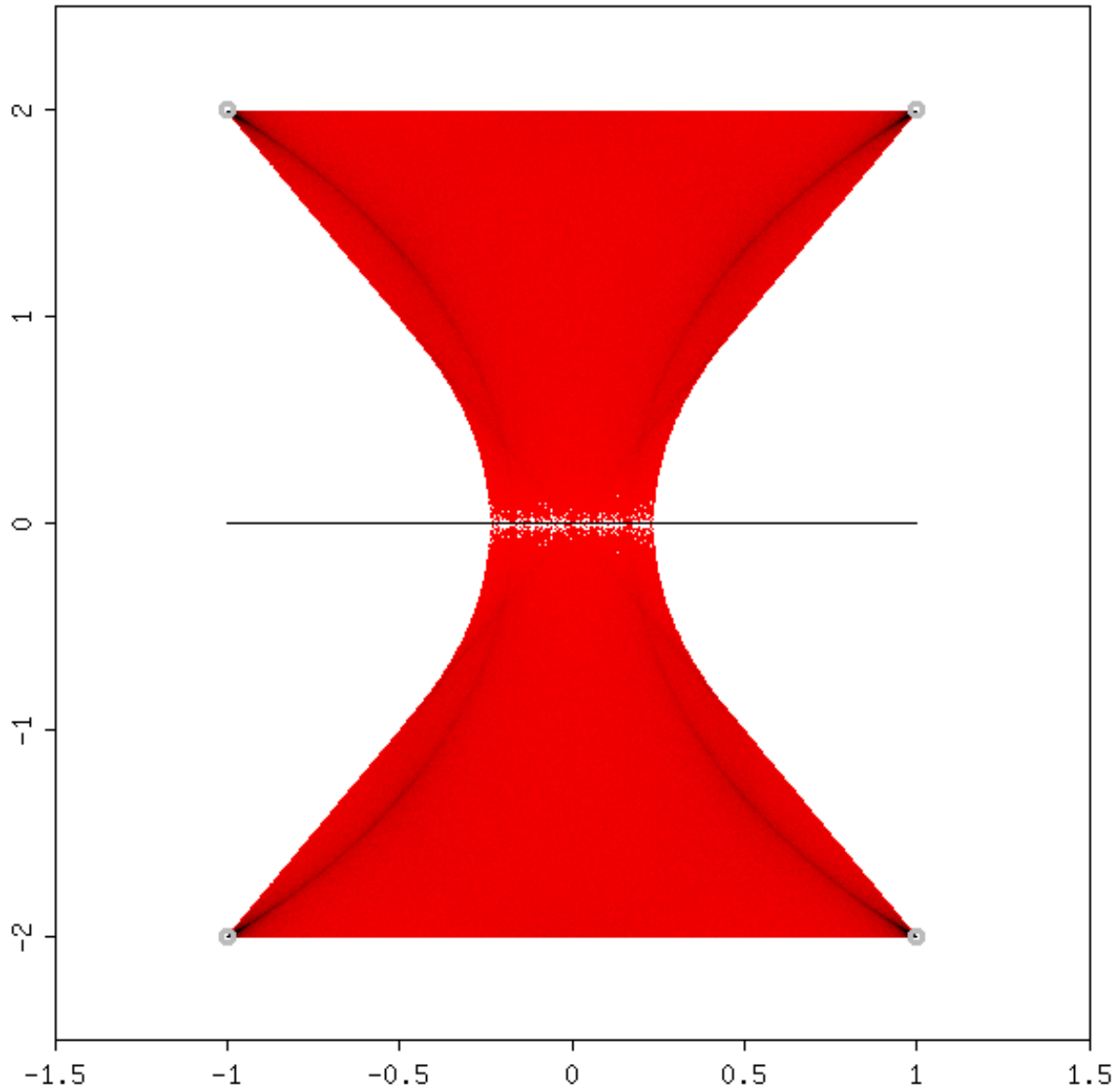
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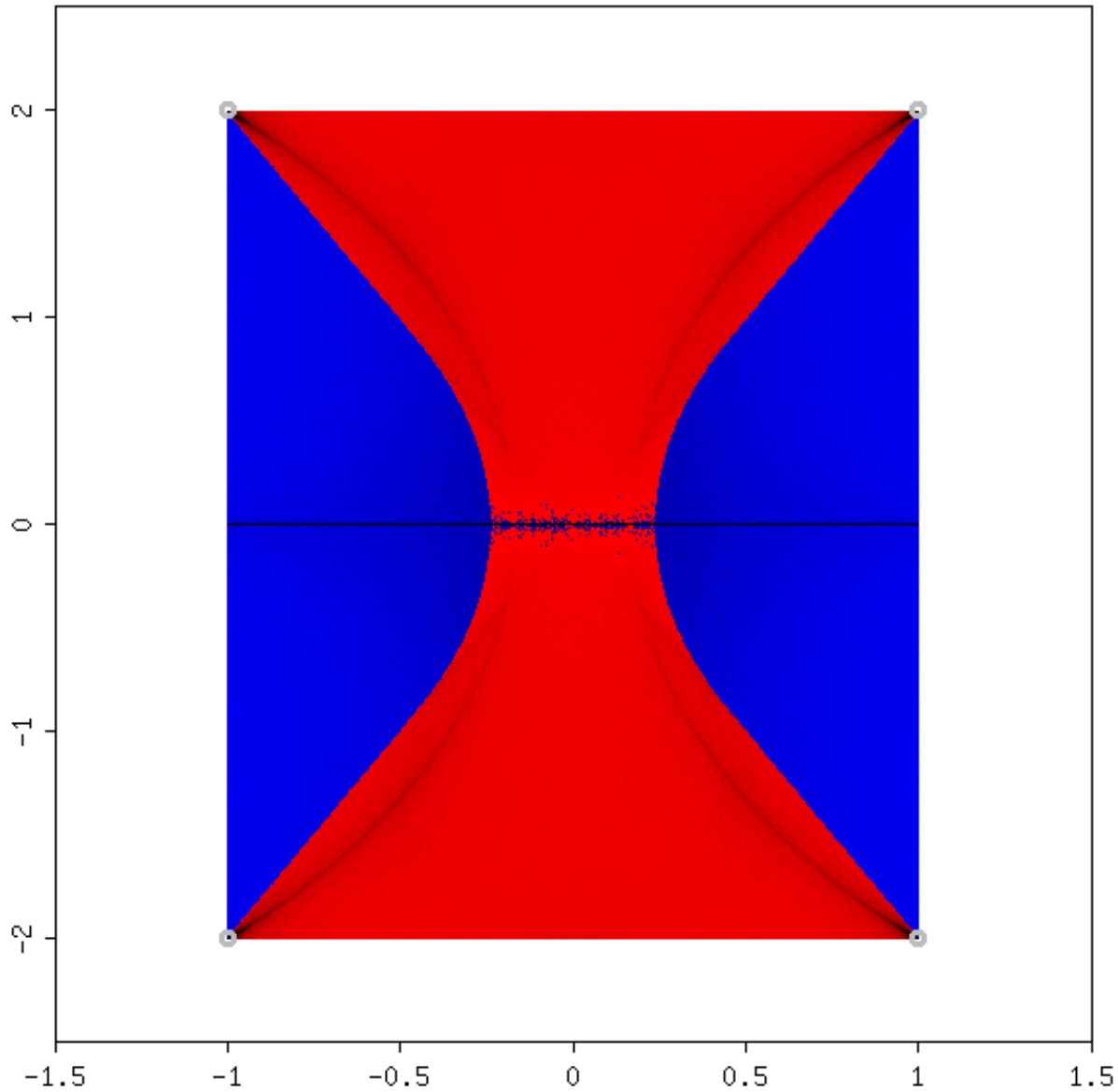
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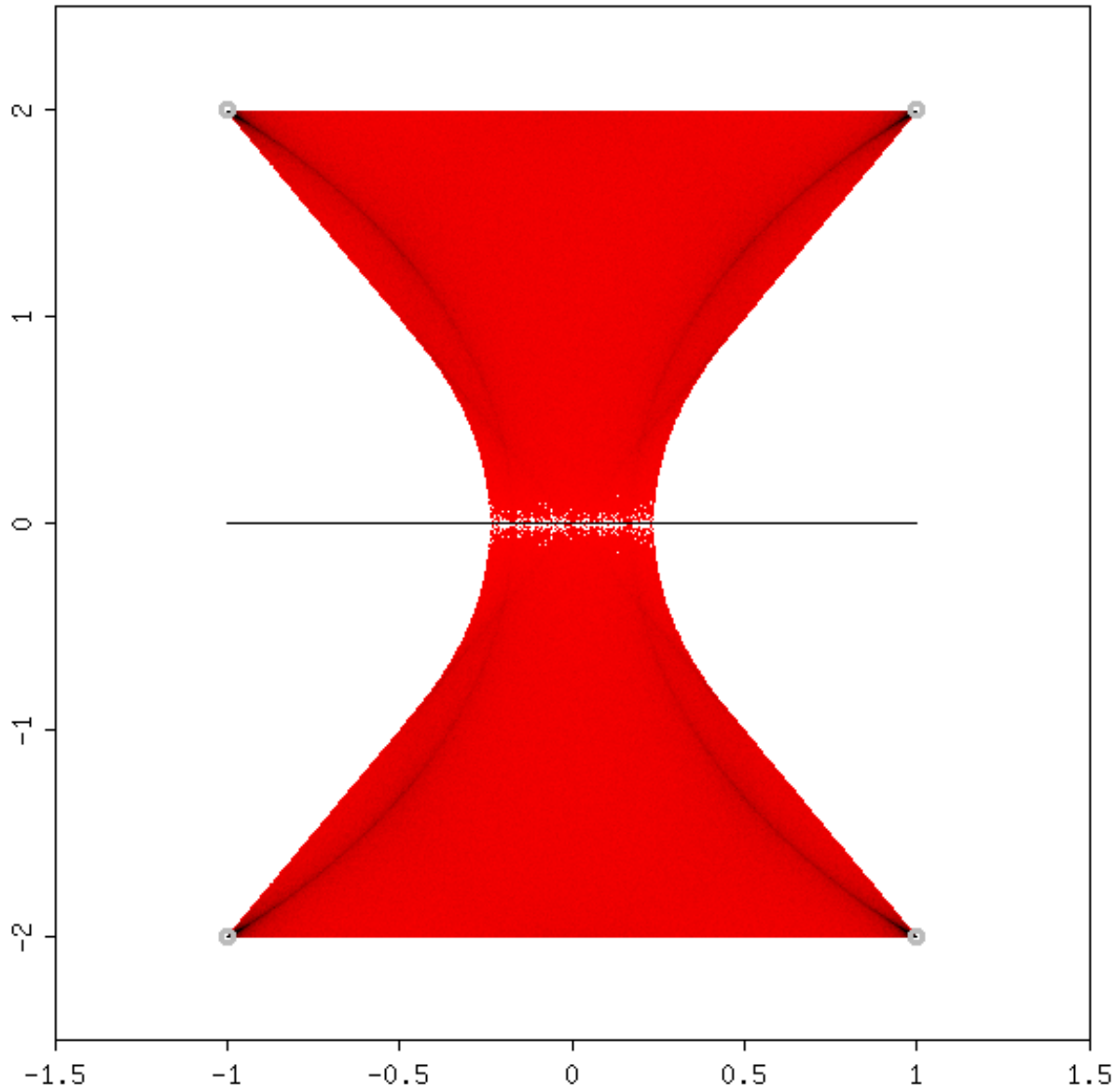


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3. Other properties [LMT'01, LMMT'01]

angle $< \pi$

Theorem 3. Let $\lambda_0 \in W^2(\mathcal{A})$ be a corner,

$$\det \left(\mathcal{A}_{x_1^0, x_2^0} - \lambda_0 \right) = 0,$$

with $x_i^0 \in \mathcal{H}_i$, $\|x_i^0\| = 1$, for $i = 1, 2$. Then either

- i) $\lambda_0 \in \sigma_p(\mathcal{A})$ with eigenvector $\begin{pmatrix} x_1^0 \\ \gamma x_2^0 \end{pmatrix}$ for some $\gamma \in \mathbb{C}$, or
- ii) $\lambda_0 \in \sigma_p(\mathcal{A})$ with eigenvector x_1^0 , or
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Theorem 5. $\dim \mathcal{H}_2 \geq 2 \implies W(A) \subset W^2(\mathcal{A}),$
 $\dim \mathcal{H}_1 \geq 2 \implies W(D) \subset W^2(\mathcal{A}).$

4. Block diagonalization [LMMT'01]

Ass. $\dim \mathcal{H}_1, \dim \mathcal{H}_2 \geq 2$, $\overline{W^2(\mathcal{A})} = \mathcal{F}_1 \dot{\cup} \mathcal{F}_2$ (w.l.o.g. $W(A) \subset \mathcal{F}_1$).

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Theorem 6.

i) *There exist $K_1 \in L(\mathcal{H}_1, \mathcal{H}_2)$, $K_2 \in L(\mathcal{H}_2, \mathcal{H}_1)$:*

$$\mathcal{L}_1 = \left\{ \begin{pmatrix} x_1 \\ K_1 x_1 \end{pmatrix} : x_1 \in \mathcal{H}_1 \right\}, \quad \mathcal{L}_2 = \left\{ \begin{pmatrix} K_2 x_2 \\ x_2 \end{pmatrix} : x_2 \in \mathcal{H}_2 \right\};$$

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ii) K_1, K_2 are solutions of **Riccati equations**, e.g.

$$K_1 B K_1 + K_1 A - D K_1 - C = 0;$$

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$$\mathcal{L}_1 = \left\{ \begin{pmatrix} x_1 \\ K_1 x_1 \end{pmatrix} : x_1 \in \mathcal{H}_1 \right\}, \quad \mathcal{L}_2 = \left\{ \begin{pmatrix} K_2 x_2 \\ x_2 \end{pmatrix} : x_2 \in \mathcal{H}_2 \right\};$$

ii) K_1, K_2 are solutions of Riccati equations, e.g.

$$K_1 B K_1 + K_1 A - D K_1 - C = 0;$$

iii) \mathcal{A} is block diagonalizable:

$$\begin{pmatrix} I & K_2 \\ K_1 & I \end{pmatrix}^{-1} \begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} I & K_2 \\ K_1 & I \end{pmatrix} = \begin{pmatrix} A + B K_1 & 0 \\ 0 & D + C K_2 \end{pmatrix}.$$

5. Block numerical range (BNR) [WT'03]

Now: $\mathcal{H} = \mathcal{H}_1 \times \cdots \times \mathcal{H}_n$ with Hilbert spaces $\mathcal{H}_1, \dots, \mathcal{H}_n$,

$$\mathcal{A} = \left(A_{ij} \right)_{i,j=1}^n = \begin{pmatrix} A_{11} & \cdots & A_{1n} \\ \vdots & \ddots & \vdots \\ A_{n1} & \cdots & A_{nn} \end{pmatrix}, \quad A_{ij} \in L(\mathcal{H}_j, \mathcal{H}_i).$$

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Definition.

$$W^n(\mathcal{A}) := \left\{ \lambda \in \mathbb{C} : \det \begin{pmatrix} (A_{11}x_1, x_1) - \lambda & \cdots & (A_{1n}x_n, x_1) \\ \vdots & \ddots & \vdots \\ (A_{n1}x_1, x_n) & \cdots & (A_{nn}x_n, x_n) - \lambda \end{pmatrix} = 0 \right. \\ \left. \text{for some } x_i \in \mathcal{H}_i, \|x_i\| = 1, i = 1, \dots, n \right\}$$

$$= \bigcup_{\|x_i\|=1} \sigma_p(\mathcal{A}_{x_1, \dots, x_n})$$

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Note: $\mathcal{A} \in M_n(\mathbb{C}) \implies \sigma(\mathcal{A}) = W^n(\mathcal{A})!$

Theorem 7. If $\hat{n} \geq n$ and $\mathcal{H} = \hat{\mathcal{H}}_1 \times \cdots \times \hat{\mathcal{H}}_{\hat{n}}$ is a "refinement" of $\mathcal{H} = \mathcal{H}_1 \times \cdots \times \mathcal{H}_n$, then

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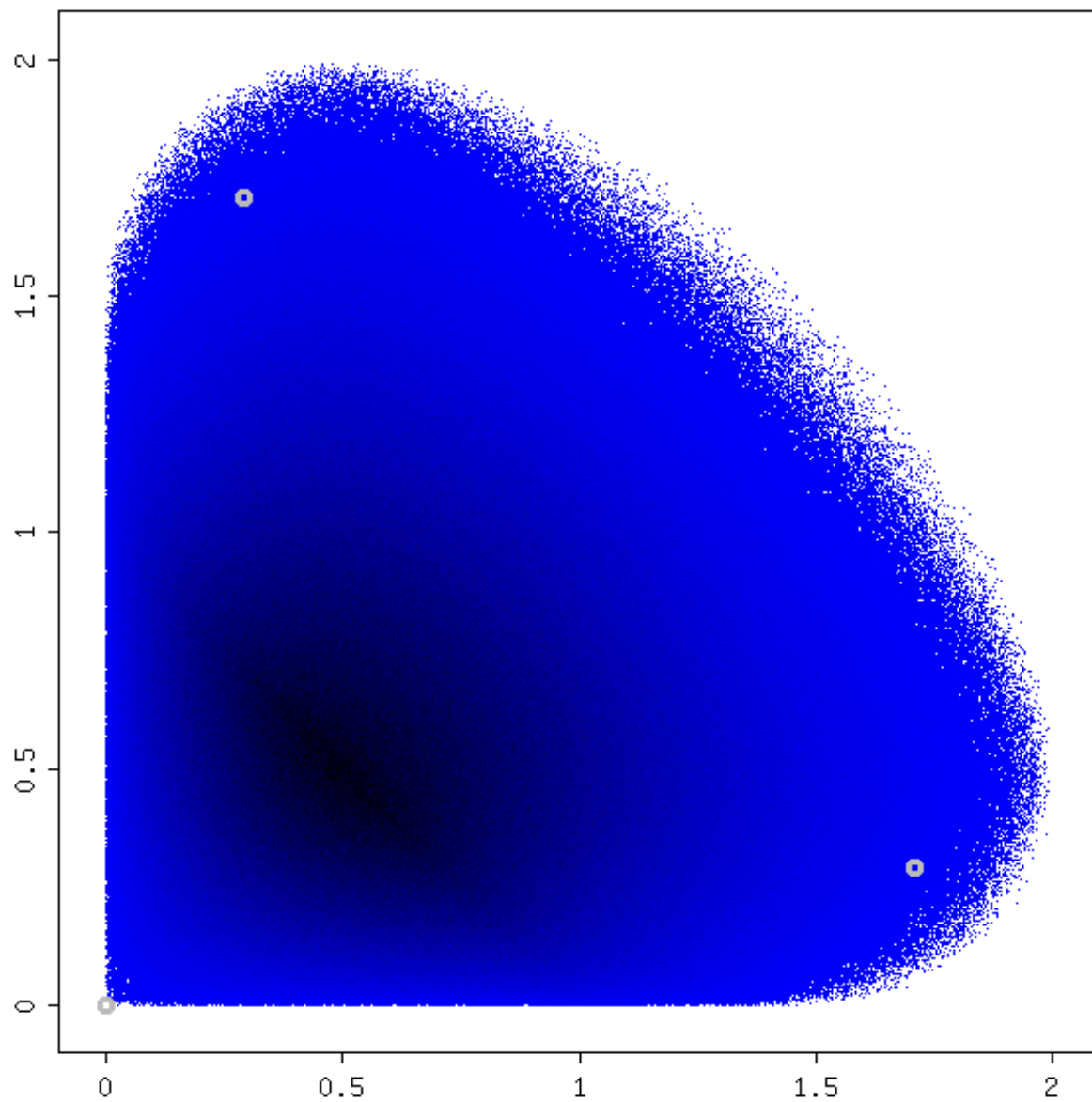
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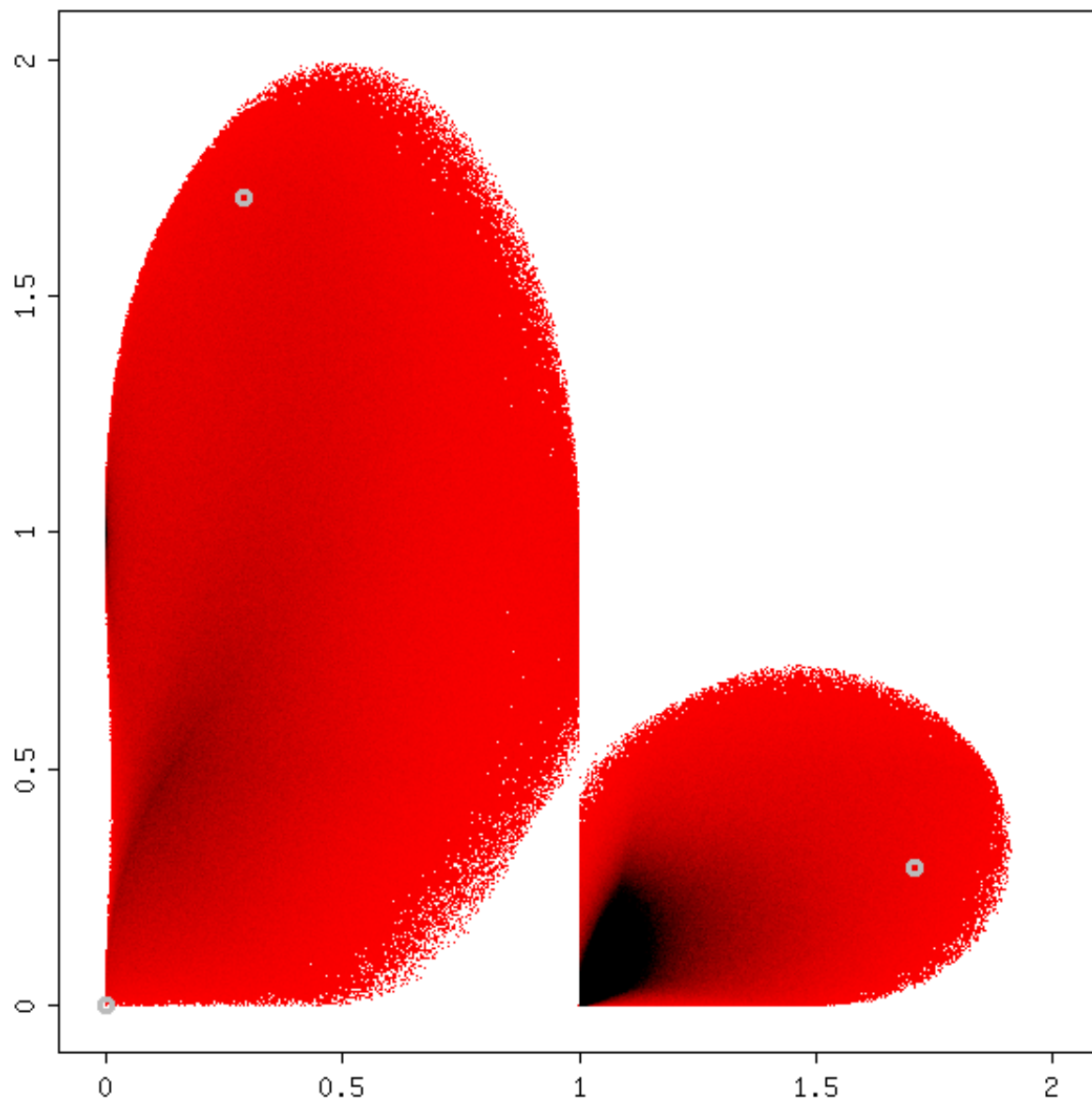
Theorem 6'. If $\dim \mathcal{H}_i \geq n$ and $\overline{W^n(\mathcal{A})} = \mathcal{F}_1 \dot{\cup} \cdots \dot{\cup} \mathcal{F}_n$ with "strongly separated" \mathcal{F}_i , then there are $K_{ij} \in L(\mathcal{H}_j, \mathcal{H}_i)$ and $Z_i \in L(\mathcal{H}_i)$ with

$$\begin{pmatrix} I & \cdots & K_{1n} \\ \vdots & \ddots & \vdots \\ K_{1n} & \cdots & I \end{pmatrix}^{-1} \begin{pmatrix} A_{11} & \cdots & A_{1n} \\ \vdots & \ddots & \vdots \\ A_{n1} & \cdots & A_{nn} \end{pmatrix} \begin{pmatrix} I & \cdots & K_{1n} \\ \vdots & \ddots & \vdots \\ K_{1n} & \cdots & I \end{pmatrix} = \begin{pmatrix} Z_1 & & 0 \\ & \ddots & \\ 0 & & Z_n \end{pmatrix}.$$



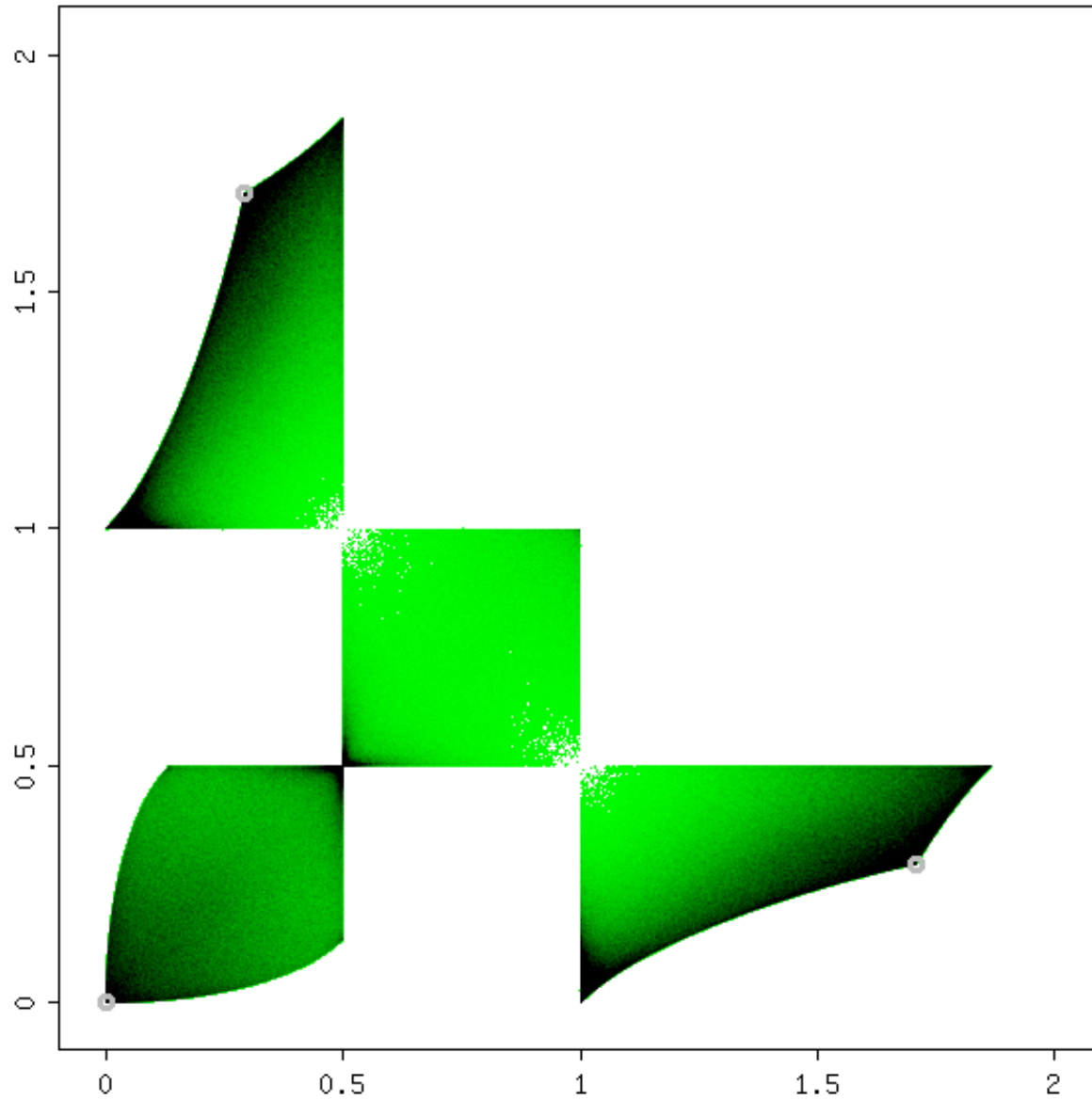
Numerical range of

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & i & 0 & 0 & i \\ 0 & 0 & 0 & i & i & 0 \\ 1 & 0 & 0 & i & 1+i & 0 \\ 0 & 1 & i & 0 & 0 & 1+i \end{pmatrix}$$



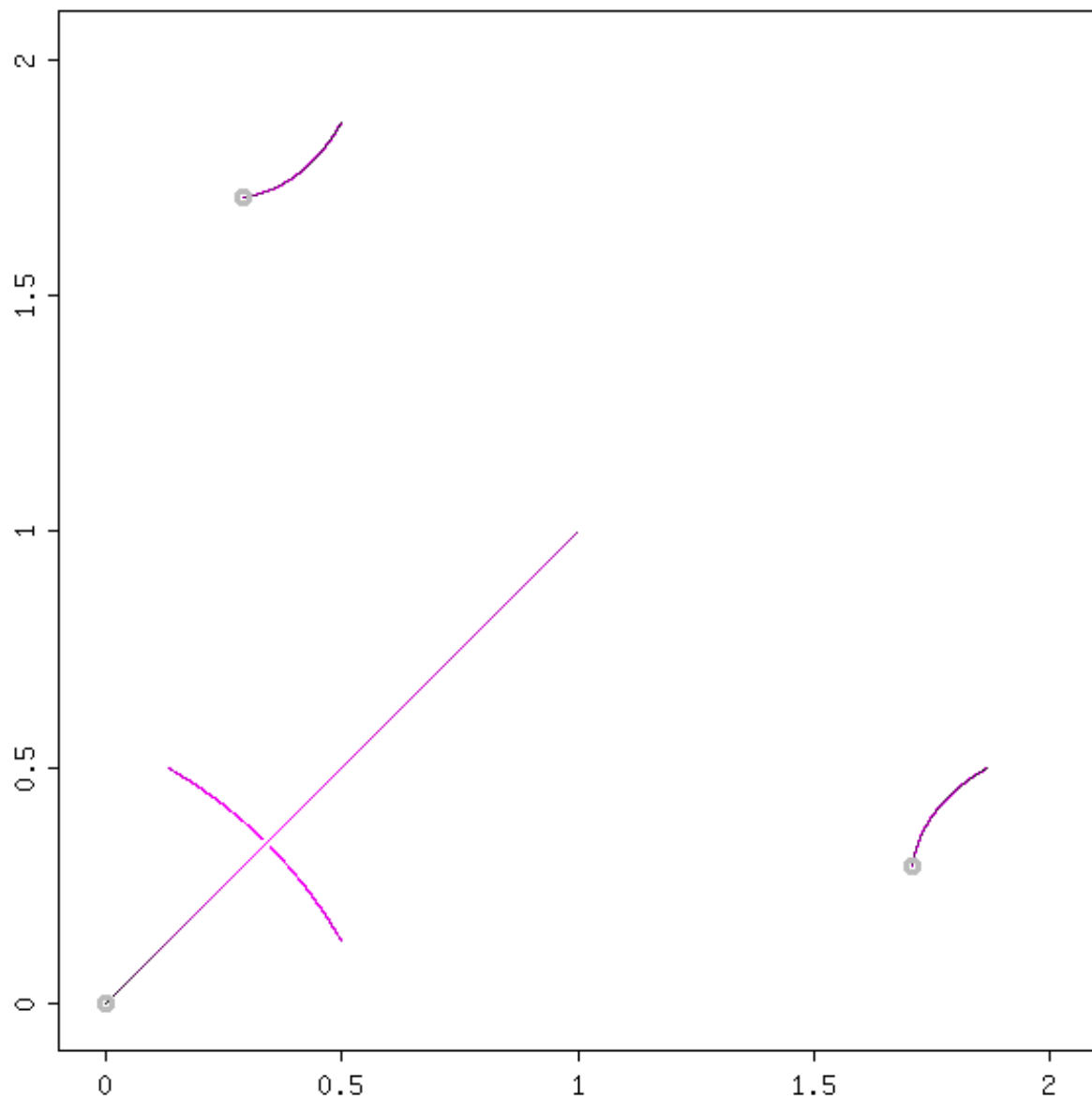
QNR of

$$\left(\begin{array}{cc|cc} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ \hline 0 & 0 & i & 0 & 0 & i \\ 0 & 0 & 0 & i & i & 0 \\ 1 & 0 & 0 & i & 1+i & 0 \\ 0 & 1 & i & 0 & 0 & 1+i \end{array} \right)$$



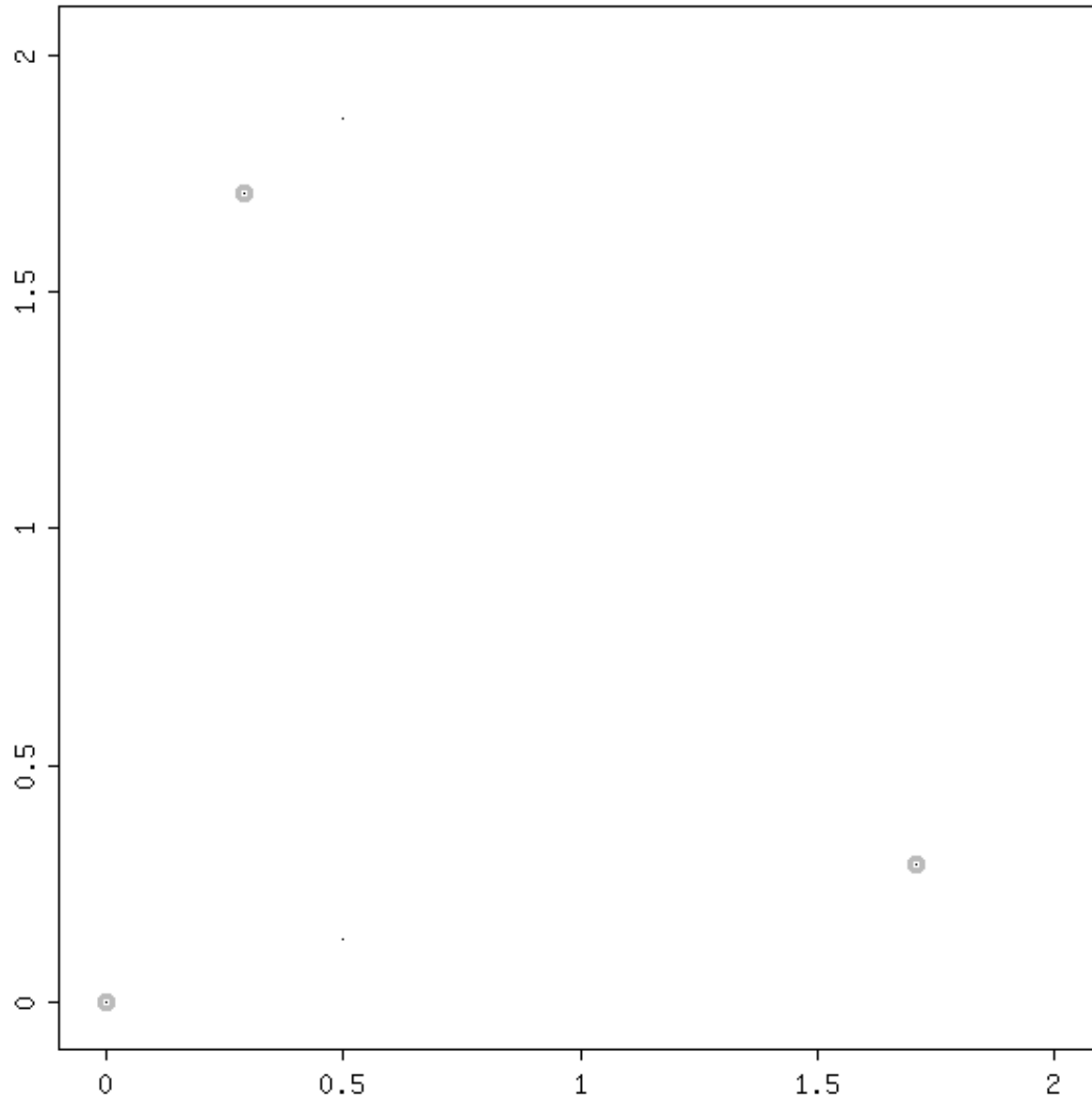
CNR of

$$\left(\begin{array}{cc|cc|cc} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ \hline 0 & 0 & i & 0 & 0 & i \\ 0 & 0 & 0 & i & i & 0 \\ \hline 1 & 0 & 0 & i & 1+i & 0 \\ 0 & 1 & i & 0 & 0 & 1+i \end{array} \right)$$



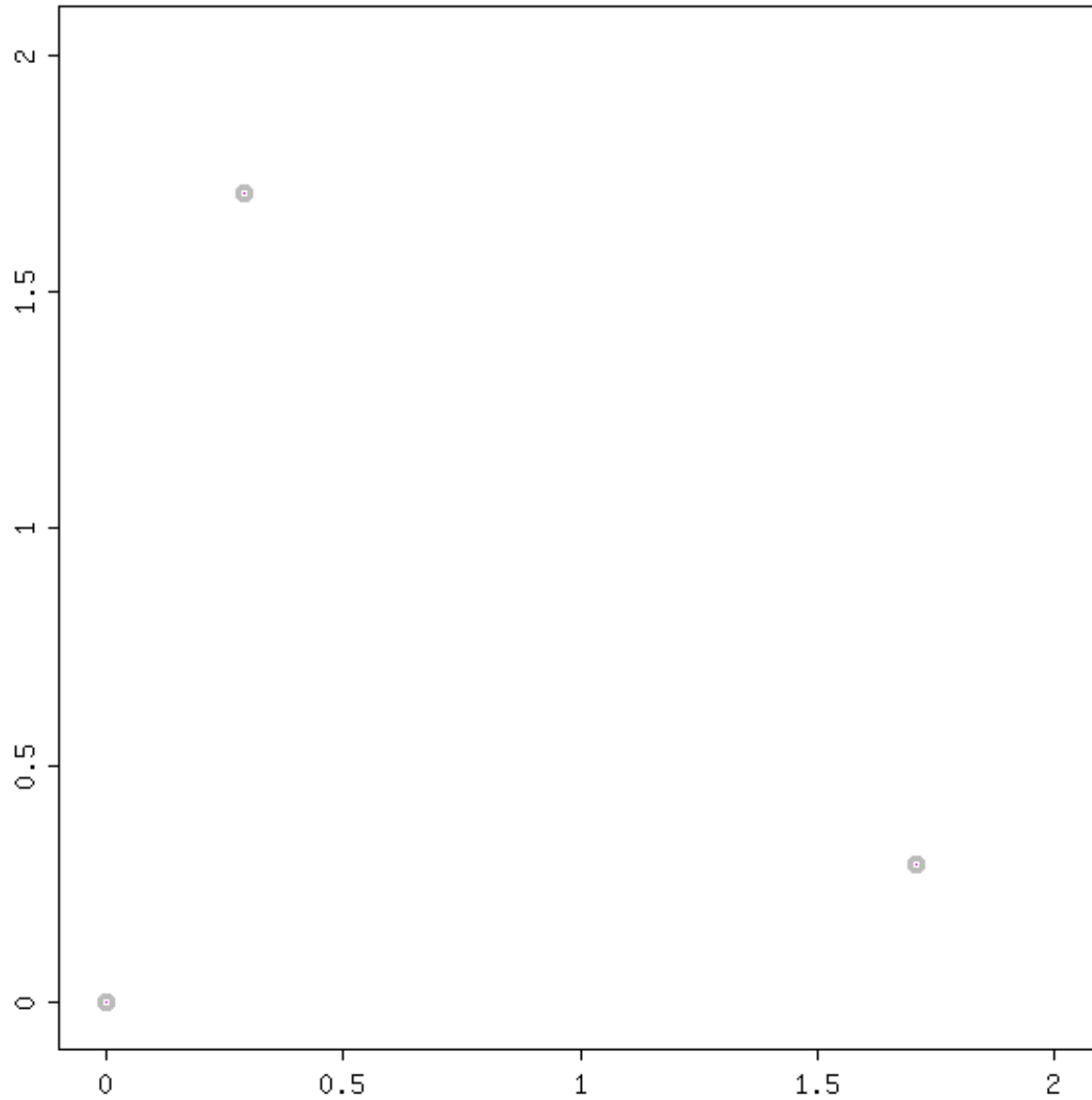
4-BNR of

$$\left(\begin{array}{cc|cc|c|c} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ \hline 0 & 0 & i & 0 & 0 & i \\ 0 & 0 & 0 & i & i & 0 \\ \hline 1 & 0 & 0 & i & 1+i & 0 \\ \hline 0 & 1 & i & 0 & 0 & 1+i \end{array} \right)$$



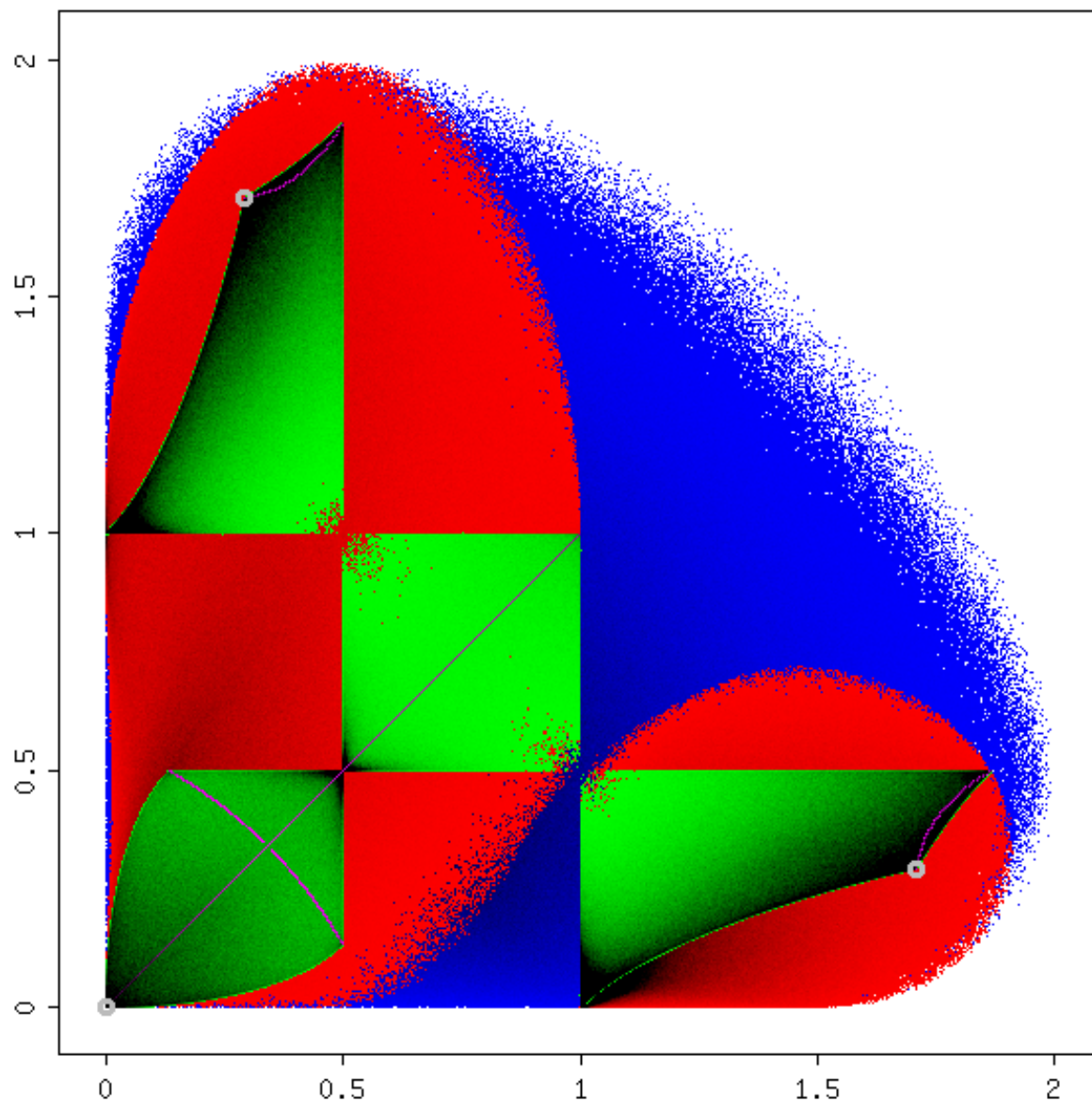
5-BNR of

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ \hline 0 & 0 & i & 0 & 0 & i \\ \hline 0 & 0 & 0 & i & i & 0 \\ \hline 1 & 0 & 0 & i & 1+i & 0 \\ \hline 0 & 1 & i & 0 & 0 & 1+i \end{pmatrix}$$



6-BNR of

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & i & 0 & 0 & i \\ 0 & 0 & 0 & i & i & 0 \\ 1 & 0 & 0 & i & 1+i & 0 \\ 0 & 1 & i & 0 & 0 & 1+i \end{pmatrix}$$



Numerical range, **QNR**,
CNR, **4-BNR**, ... of

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Further results and work in progress [T'08]

- BNR of companion operators and NR of operator polynomials;
- Variational principles for eigenvalues in spectral gaps;
- QNR for unbounded block operator matrices;
- QNR and BNR for analytic block operator matrix functions like

$$\mathcal{A}(\lambda) = \begin{pmatrix} A(\lambda) & B(\lambda) \\ C(\lambda) & D(\lambda) \end{pmatrix} \quad \text{in } \mathcal{H}_1 \times \mathcal{H}_2;$$

Open problems:

- Can a component of $W^2(\mathcal{A})$ have a hole?
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