## Cauchy-Riemann

## Equations and

## Conformal Mapping

## 4 <br> Introduction

In this Section we consider two important features of complex functions. The Cauchy-Riemann equations provide a necessary and sufficient condition for a function $f(z)$ to be analytic in some region of the complex plane; this allows us to find $f^{\prime}(z)$ in that region by the rules of the previous Section.

A mapping between the $z$-plane and the $w$-plane is said to be conformal if the angle between two intersecting curves in the $z$-plane is equal to the angle between their mappings in the $w$-plane. Such a mapping has widespread uses in solving problems in fluid flow and electromagnetics, for example, where the given problem geometry is somewhat complicated.

Prerequisites
Before starting this Section you should ...

## Learning Outcomes

On completion you should be able to ..

- understand the idea of a complex function and its derivative
- use the Cauchy-Riemann equations to obtain the derivative of complex functions
- appreciate the idea of a conformal mapping


## 1. The Cauchy-Riemann equations

Remembering that $z=x+\mathrm{i} y$ and $w=u+\mathrm{i} v$, we note that there is a very useful test to determine whether a function $w=f(z)$ is analytic at a point. This is provided by the Cauchy-Riemann equations. These state that $w=f(z)$ is differentiable at a point $z=z_{0}$ if, and only if,

$$
\frac{\partial u}{\partial x}=\frac{\partial v}{\partial y} \quad \text { and } \quad \frac{\partial u}{\partial y}=-\frac{\partial v}{\partial x} \quad \text { at that point. }
$$

When these equations hold then it can be shown that the complex derivative may be determined by using either $\frac{d f}{d z}=\frac{\partial f}{\partial x}$ or $\frac{d f}{d z}=-\mathrm{i} \frac{\partial f}{\partial y}$.
(The use of 'if, and only if,' means that if the equations are valid, then the function is differentiable and vice versa.)
If we consider $f(z)=z^{2}=x^{2}-y^{2}+2 \mathrm{i} x y$ then $u=x^{2}-y^{2}$ and $v=2 x y$ so that

$$
\frac{\partial u}{\partial x}=2 x, \quad \frac{\partial u}{\partial y}=-2 y, \quad \frac{\partial v}{\partial x}=2 y, \quad \frac{\partial v}{\partial y}=2 x .
$$

It should be clear that, for this example, the Cauchy-Riemann equations are always satisfied; therefore, the function is analytic everywhere. We find that

$$
\frac{d f}{d z}=\frac{\partial f}{\partial x}=2 x+2 \mathrm{i} y=2 z \quad \text { or, equivalently, } \quad \frac{d f}{d z}=-\mathrm{i} \frac{\partial f}{\partial y}=-\mathrm{i}(-2 y+2 \mathrm{i} x)=2 z
$$

This is the result we would expect to get by simply differentiating $f(z)$ as if it was a real function. For analytic functions this will always be the case i.e. for an analytic function $f^{\prime}(z)$ can be found using the rules for differentiating real functions.

## Example 3

Show that the function $f(z)=z^{3}$ is analytic everwhere and hence obtain its derivative.

## Solution

$$
w=f(z)=(x+\mathrm{i} y)^{3}=x^{3}-3 x y^{2}+\left(3 x^{2} y-y^{3}\right) \mathrm{i}
$$

Hence

$$
u=x^{3}-3 x y^{2} \quad \text { and } \quad v=3 x^{2} y-y^{3} .
$$

Then

$$
\frac{\partial u}{\partial x}=3 x^{2}-3 y^{2}, \quad \frac{\partial u}{\partial y}=-6 x y, \quad \frac{\partial v}{\partial x}=6 x y, \quad \frac{\partial v}{\partial y}=3 x^{2}-3 y^{2} .
$$

The Cauchy-Riemann equations are identically true and $f(z)$ is analytic everywhere.
Furthermore $\quad \frac{d f}{d z}=\frac{\partial f}{\partial x}=3 x^{2}-3 y^{2}+(6 x y) \mathrm{i}=3(x+\mathrm{i} y)^{2}=3 z^{2} \quad$ as we would expect.

We can easily find functions which are not analytic anywhere and others which are only analytic in a restricted region of the complex plane. Consider again the function $f(z)=\bar{z}=x-\mathrm{i} y$.

Here

$$
u=x \quad \text { so that } \quad \frac{\partial u}{\partial x}=1, \quad \text { and } \quad \frac{\partial u}{\partial y}=0 ; \quad v=-y \quad \text { so that } \quad \frac{\partial v}{\partial x}=0, \quad \frac{\partial v}{\partial y}=-1 .
$$

The Cauchy-Riemann equations are never satisfied so that $\bar{z}$ is not differentiable anywhere and so is not analytic anywhere.
By contrast if we consider the function $f(z)=\frac{1}{z}$ we find that

$$
u=\frac{x}{x^{2}+y^{2}} ; \quad v=\frac{y}{x^{2}+y^{2}} .
$$

As can readily be shown, the Cauchy-Riemann equations are satisfied everywhere except for $x^{2}+y^{2}=$ 0 , i.e. $x=y=0$ (or, equivalently, $z=0$.) At all other points $f^{\prime}(z)=-\frac{1}{z^{2}}$. This function is analytic everywhere except at the single point $z=0$.

Analyticity is a very powerful property of a function of a complex variable. Such functions tend to behave like functions of a real variable.

## Example 4

Show that if $f(z)=z \bar{z}$ then $f^{\prime}(z)$ exists only at $z=0$.

## Solution

$f(z)=x^{2}+y^{2}$ so that $u=x^{2}+y^{2}, \quad v=0 . \quad \frac{\partial u}{\partial x}=2 x, \quad \frac{\partial u}{\partial y}=2 y, \quad \frac{\partial v}{\partial x}=0, \quad \frac{\partial v}{\partial y}=0$.
Hence the Cauchy-Riemann equations are satisfied only where $x=0$ and $y=0$, i.e. where $z=0$. Therefore this function is not analytic anywhere.

## Analytic functions and harmonic functions

Using the Cauchy-Riemann equations in a region of the $z$-plane where $f(z)$ is analytic, gives

$$
\frac{\partial^{2} u}{\partial x \partial y}=\frac{\partial}{\partial x}\left(\frac{\partial u}{\partial y}\right)=\frac{\partial}{\partial x}\left(-\frac{\partial v}{\partial x}\right)=-\frac{\partial^{2} v}{\partial x^{2}}
$$

and

$$
\frac{\partial^{2} u}{\partial y \partial x}=\frac{\partial}{\partial y}\left(\frac{\partial u}{\partial x}\right)=\frac{\partial}{\partial y}\left(\frac{\partial v}{\partial y}\right)=\frac{\partial^{2} v}{\partial y^{2}} .
$$

If these differentiations are possible then $\frac{\partial^{2} u}{\partial x \partial y}=\frac{\partial^{2} u}{\partial y \partial x}$ so that

$$
\frac{\partial^{2} u}{\partial x^{2}}+\frac{\partial^{2} u}{\partial y^{2}}=0 \quad \text { (Laplace's equation) }
$$

In a similar way we find that

$$
\frac{\partial^{2} v}{\partial x^{2}}+\frac{\partial^{2} v}{\partial y^{2}}=0 \quad(\text { Can you show this? })
$$

When $f(z)$ is analytic the functions $u$ and $v$ are called conjugate harmonic functions.
Suppose $u=u(x, y)=x y$ then it is easy to verify that $u$ satisfies Laplace's equation (try this). We now try to find the conjugate harmonic function $v=v(x, y)$.
First, using the Cauchy-Riemann equations:

$$
\frac{\partial v}{\partial y}=\frac{\partial u}{\partial x}=y \quad \text { and } \quad \frac{\partial v}{\partial x}=-\frac{\partial u}{\partial y}=-x .
$$

Integrating the first equation gives $v=\frac{1}{2} y^{2}+$ a function of $x$. Integrating the second equation gives $v=-\frac{1}{2} x^{2}+$ a function of $y$. Bearing in mind that an additive constant leaves no trace after differentiation, we pool the information above to obtain

$$
v=\frac{1}{2}\left(y^{2}-x^{2}\right)+C \quad \text { where } C \text { is a constant }
$$

Note that $f(z)=u+\mathrm{i} v=x y+\frac{1}{2}\left(y^{2}-x^{2}\right) \mathbf{i}+D$ where $D$ is a constant (replacing $C \mathbf{i}$ ).
We can write $f(z)=-\frac{1}{2} \mathrm{i} z^{2}+D$ (as you can verify). This function is analytic everywhere.

Given the function $u=x^{2}-x-y^{2}$
(a) Show that $u$ is harmonic, (b) Find the conjugate harmonic function, $v$.

## Your solution

(a)

## Answer

$$
\frac{\partial u}{\partial x}=2 x-1, \quad \frac{\partial^{2} u}{\partial x^{2}}=2, \quad \frac{\partial u}{\partial y}=-2 y, \quad \frac{\partial^{2} u}{\partial y^{2}}=-2 .
$$

Hence $\quad \frac{\partial^{2} u}{\partial x^{2}}+\frac{\partial^{2} u}{\partial y^{2}}=0$ and $u$ is harmonic.

## Your solution

(b)

## Answer

Integrating $\frac{\partial v}{\partial y}=2 x-1$ gives $v=2 x y-y+$ function of $x$.
Integrating $\frac{\partial v}{\partial x}=+2 y$ gives $v=2 x y+$ function of $y$.
Ignoring the duplication, $v=2 x y-y+C$, where $C$ is a constant.

Find $f(z)$ in terms of $z$, where $f(z)=u+\mathrm{i} v$, where $u$ and $v$ are those found in the previous Task.

## Your solution

## Answer

$f(z)=u+i v=x^{2}-x-y^{2}+2 x y \mathrm{i}-\mathrm{i} y+D, \quad D$ constant.
Now $\quad z^{2}=x^{2}-y^{2}+2 \mathrm{i} x y$ and $z=x+\mathrm{i} y$ thus $f(z)=z^{2}-z+D$.

## Exercises

1. Find the singular point of the rational function $f(z)=\frac{z}{z-2 \mathrm{i}}$. Find $f^{\prime}(z)$ at other points and evaluate $f^{\prime}(-\mathrm{i})$.
2. Show that the function $f(z)=z^{2}+z$ is analytic everywhere and hence obtain its derivative.
3. Show that the function $u=x^{2}-y^{2}-2 y$ is harmonic, find the conjugate harmonic function $v$ and hence find $f(z)=u+\mathrm{i} v$ in terms of $z$.

## Answers

1. $f(z)$ is singular at $z=2$ i. Elsewhere

$$
f^{\prime}(z)=\frac{(z-2 \mathrm{i}) \cdot 1-z \cdot 1}{(z-2 \mathrm{i})^{2}}=\frac{-2 \mathrm{i}}{(z-2 \mathrm{i})^{2}} \quad f^{\prime}(-\mathrm{i})=\frac{-2 \mathrm{i}}{(-3 \mathrm{i})^{2}}=\frac{-2 \mathrm{i}}{-9}=\frac{2}{9} \mathrm{i}
$$

2. $u=x^{2}+x-y^{2}$ and $v=2 x y+y$

$$
\frac{\partial u}{\partial x}=2 x+1, \quad \frac{\partial u}{\partial y}=-2 y, \quad \frac{\partial v}{\partial x}=2 y, \quad \frac{\partial v}{\partial y}=2 x+1
$$

Here the Cauchy-Riemann equations are identically true and $f(z)$ is analytic everywhere.

$$
\frac{d f}{d z}=\frac{\partial f}{\partial x}=2 x+1+2 y \mathbf{i}=2 z+1
$$

## Answer

3. $\frac{\partial^{2} u}{\partial x^{2}}=2, \quad \frac{\partial^{2} u}{\partial y^{2}}=-2 \quad$ therefore $u$ is harmonic.

$$
\frac{\partial v}{\partial y}=\frac{\partial u}{\partial x}=2 x \quad \text { therefore } v=2 x y+\text { function of } y
$$

$$
\frac{\partial v}{\partial x}=-\frac{\partial u}{\partial y}=2 y+2 \quad \text { therefore } v=2 x y+2 x+\text { function of } x
$$

$$
\therefore \quad v=2 x y+2 x+\text { constant }
$$

$$
f(z)=x^{2}+2 \mathbf{i} x y-y^{2}+2 x \mathbf{i}-2 y=z^{2}+2 \mathrm{i} z
$$

## 2. Conformal mapping

In Section 26.1 we saw that the real and imaginary parts of an analytic function each satisfies Laplace's equation. We shall show now that the curves

$$
u(x, y)=\text { constant } \quad \text { and } \quad v(x, y)=\text { constant }
$$

intersect each other at right angles (i.e. are orthogonal). To see this we note that along the curve $u(x, y)=$ constant we have $d u=0$. Hence

$$
d u=\frac{\partial u}{\partial x} d x+\frac{\partial u}{\partial y} d y=0 .
$$

Thus, on these curves the gradient at a general point is given by

$$
\frac{d y}{d x}=-\frac{\frac{\partial u}{\partial x}}{\frac{\partial u}{\partial y}}
$$

Similarly along the curve $v(x, y)=$ constant, we have

$$
\frac{d y}{d x}=-\frac{\frac{\partial v}{\partial x}}{\frac{\partial v}{\partial y}}
$$

The product of these gradients is

$$
\frac{\left(\frac{\partial u}{\partial x}\right)\left(\frac{\partial v}{\partial x}\right)}{\left(\frac{\partial u}{\partial y}\right)\left(\frac{\partial v}{\partial y}\right)}=-\frac{\left(\frac{\partial u}{\partial x}\right)\left(\frac{\partial u}{\partial y}\right)}{\left(\frac{\partial u}{\partial y}\right)\left(\frac{\partial u}{\partial x}\right)}=-1
$$

where we have made use of the Cauchy-Riemann equations. We deduce that the curves are orthogonal.

As an example of the practical application of this work consider two-dimensional electrostatics. If $u=$ constant gives the equipotential curves then the curves $v=$ constant are the electric lines of force. Figure 2 shows some curves from each set in the case of oppositely-charged particles near to each other; the dashed curves are the lines of force and the solid curves are the equipotentials.


Figure 2
In ideal fluid flow the curves $v=$ constant are the streamlines of the flow.
In these situations the function $w=u+\mathrm{i} v$ is the complex potential of the field.

## Function as mapping

A function $w=f(z)$ can be regarded as a mapping, which maps a point in the $z$-plane to a point in the $w$-plane. Curves in the $z$-plane will be mapped into curves in the $w$-plane.

Consider aerodynamics where we are interested in the fluid flow in a complicated geometry (say flow past an aerofoil). We first find the flow in a simple geometry that can be mapped to the aerofoil shape (the complex plane with a circular hole works here). Most of the calculations necessary to find physical characteristics such as lift and drag on the aerofoil can be performed in the simple geometry - the resulting integrals being much easier to evaluate than in the complicated geometry.

Consider the mapping

$$
w=z^{2} .
$$

The point $z=2+\mathrm{i}$ maps to $w=(2+\mathrm{i})^{2}=3+4 \mathrm{i}$. The point $z=2+\mathrm{i}$ lies on the intersection of the two lines $x=2$ and $y=1$. To what curves do these map? To answer this question we note that a point on the line $y=1$ can be written as $z=x+\mathrm{i}$. Then

$$
w=(x+\mathrm{i})^{2}=x^{2}-1+2 x \mathrm{i}
$$

As usual, let $w=u+\mathrm{i} v$, then

$$
u=x^{2}-1 \quad \text { and } \quad v=2 x
$$

Eliminating $x$ we obtain:

$$
4 u=4 x^{2}-4=v^{2}-4 \quad \text { so } \quad v^{2}=4+4 u \text { is the curve to which } y=1 \text { maps. }
$$

## Example 5

Onto what curve does the line $x=2$ map?

## Solution

A point on the line is $z=2+y$ i. Then

$$
w=(2+y \mathbf{i})^{2}=4-y^{2}+4 y \mathbf{i}
$$

Hence $u=4-y^{2}$ and $v=4 y$ so that, eliminating $y$ we obtain

$$
16 u=64-v^{2} \quad \text { or } \quad v^{2}=64-16 u
$$

In Figure 3(a) we sketch the lines $x=2$ and $y=1$ and in Figure 3(b) we sketch the curves into which they map. Note these curves intersect at the point $(3,4)$.


Figure 3
The angle between the original lines in (a) is clearly $90^{\circ}$; what is the angle between the curves in (b) at the point of intersection?

The curve $v^{2}=4+4 u$ has a gradient $\frac{d v}{d u}$. Differentiating the equation implicitly we obtain

$$
2 v \frac{d v}{d u}=4 \quad \text { or } \quad \frac{d v}{d u}=\frac{2}{v}
$$

At the point $(3,4) \frac{d v}{d u}=\frac{1}{2}$.

Find $\frac{d v}{d u}$ for the curve $v^{2}=64-16 u$ and evaluate it at the point $(3,4)$.

## Your solution

## Answer

$$
2 v \frac{d v}{d u}=-16 \quad \therefore \quad \frac{d v}{d u}=-\frac{8}{v} \text {. At } v=4 \text { we obtain } \frac{d v}{d u}=-2 \text {. }
$$

Note that the product of the gradients at $(3,4)$ is -1 and therefore the angle between the curves at their point of intersection is also $90^{\circ}$. Since the angle between the lines and the angle between the curves is the same we say the angle is preserved.

In general, if two curves in the $z$-plane intersect at a point $z_{0}$, and their image curves under the mapping $w=f(z)$ intersect at $w_{0}=f\left(z_{0}\right)$ and the angle between the two original curves at $z_{0}$ equals the angle between the image curves at $w_{0}$ we say that the mapping is conformal at $z_{0}$.

An analytic function is conformal everywhere except where $f^{\prime}(z)=0$.

At which points is $w=e^{z}$ not conformal?

## Your solution

## Answer

$f^{\prime}(z)=e^{z}$. Since this is never zero the mapping is conformal everywhere.

## Inversion

The mapping $\quad w=f(z)=\frac{1}{z} \quad$ is called an inversion. It maps the interior of the unit circle in the $z$-plane to the exterior of the unit circle in the $w$-plane, and vice-versa. Note that

$$
w=u+\mathrm{i} v=\frac{x}{x^{2}+y^{2}}-\frac{y}{x^{2}+y^{2}} \mathrm{i} \quad \text { and similarly } \quad z=x+\mathrm{i} y=\frac{u}{u^{2}+v^{2}}-\frac{v}{u^{2}+v^{2}} \mathrm{i}
$$

so that

$$
u=\frac{x}{x^{2}+y^{2}} \quad \text { and } \quad v=-\frac{y}{x^{2}+y^{2}} .
$$

A line through the origin in the $z$-plane will be mapped into a line through the origin in the $w$-plane. To see this, consider the line $y=m x$, for $m$ constant. Then

$$
u=\frac{x}{x^{2}+m^{2} x^{2}} \quad \text { and } \quad v=-\frac{m x}{x^{2}+m^{2} x^{2}}
$$

so that $v=-m u$, which is a line through the origin in the $w$-plane.


Consider the line $a x+b y+c=0$ where $c \neq 0$. This represents a line in the $z$-plane which does not pass through the origin. To what type of curve does it map in the $w$-plane?

## Your solution

## Answer

The mapped curve is

$$
\frac{a u}{u^{2}+v^{2}}-\frac{b v}{u^{2}+v^{2}}+c=0
$$

Hence $a u-b v+c\left(u^{2}+v^{2}\right)=0$. Dividing by $c$ we obtain the equation:

$$
u^{2}+v^{2}+\frac{a}{c} u-\frac{b}{c} v=0
$$

which is the equation of a circle in the $w$-plane which passes through the origin.

Similarly, it can be shown that a circle in the $z$-plane passing through the origin maps to a line in the $w$-plane which does not pass through the origin. Also a circle in the $z$-plane which does not pass through the origin maps to a circle in the $w$-plane which does pass through the origin. The inversion mapping is an example of the bilinear transformation:

$$
\begin{aligned}
& \quad w=f(z)=\frac{a z+b}{c z+d} \quad \text { where we demand that } \quad a d-b c \neq 0 \\
& \text { (If } a d-b c=0 \text { the mapping reduces to } f(z)=\text { constant.) }
\end{aligned}
$$

Find the set of bilinear transformations $w=f(z)=\frac{a z+b}{c z+d}$ which map $z=2$ to $w=1$.

## Your solution

## Answer

$1=\frac{2 a+b}{2 c+d}$. Hence $2 a+b=2 c+d$.
Any values of $a, b, c, d$ satisfying this equation will do provided $a d-b c \neq 0$.

## Your solution

## Answer

$3=\frac{-a+b}{-c+d}$. Hence $-a+b=-3 c+3 d$.

## Example 6

Find the bilinear transformation which maps
(a) $z=2$ to $w=1$, and
(b) $z=-1$ to $w=3$, and
(c) $z=0$ to $w=-5$

## Solution

We have the answers to (a) and (b) from the previous two Tasks:

$$
\begin{aligned}
2 a+b & =2 c+d \\
-a+b & =-3 c+3 d
\end{aligned}
$$

If $z=0$ is mapped to $w=-5$ then $-5=\frac{b}{d}$ so that $b=-5 d$. Substituting this last relation into the first two obtained we obtain

$$
\begin{aligned}
2 a-2 c-6 d & =0 \\
-a+3 c-8 d & =0
\end{aligned}
$$

Solving these two in terms of $d$ we find $2 c=11 d$ and $2 a=17 d$. Hence the transformation is:
$w=\frac{17 z-10}{11 z+2}$ (note that the $d$ 's cancel in the numerator and denominator).

Some other mappings are shown in Figure 4.


Figure 4
As an engineering application we consider the Joukowski transformation

$$
w=z-\frac{\ell^{2}}{z} \quad \text { where } \ell \text { is a constant. }
$$

It is used to map circles which contain $z=1$ as an interior point and which pass through $z=-1$ into shapes resembling aerofoils. Figure 5 shows an example:



Figure 5
This creates a cusp at which the associated fluid velocity can be infinite. This can be avoided by adjusting the fluid flow in the $z$-plane. Eventually, this can be used to find the lift generated by such an aerofoil in terms of physical characteristics such as aerofoil shape and air density and speed.

## Exercise

Find a bilinear transformation $w=\frac{a z+b}{c z+d}$ which maps
(a) $z=0$ into $w=\mathrm{i}$
(b) $z=-1$ into $w=0$
(c) $z=-\mathrm{i}$ into $w=1$

## Answer

(a) $z=0, w=\mathrm{i}$ gives $\mathrm{i}=\frac{b}{d}$ so that $b=d \mathrm{i}$
(b) $z=-1, w=0$ gives $0=\frac{-a+b}{-c+d}$ so $-a+b=0$ so $a=b$.
(c) $z=-\mathrm{i}, w=1$ gives $1=\frac{-a \mathbf{i}+b}{-c \mathbf{i}+d}$ so that $-c \mathbf{i}+d=-a \mathbf{i}+b=d+d \mathrm{i}$ (using (a) and (b))

We conclude from (c) that $-c=d$. We also know that $a=b=d \mathrm{i}$.
Hence $w=\frac{d \mathrm{i} z+d \mathrm{i}}{-d z+d}=\frac{\mathrm{i} z+\mathrm{i}}{-z+1}$

